



# **Numerical Simulation of the Performances of Centrifugal Pumps on a Numerical Test Rig**



# Content

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## 1. Motivation

## 2. Numerical test rig „IDS“

- Geometric Set, Preprocessing and grid generation

## 3. Simulation approaches

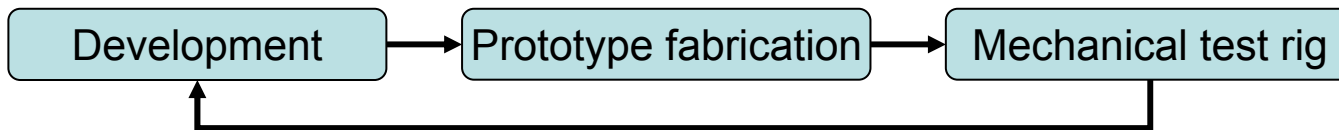
- Level of detail
- Fluid flow modeling



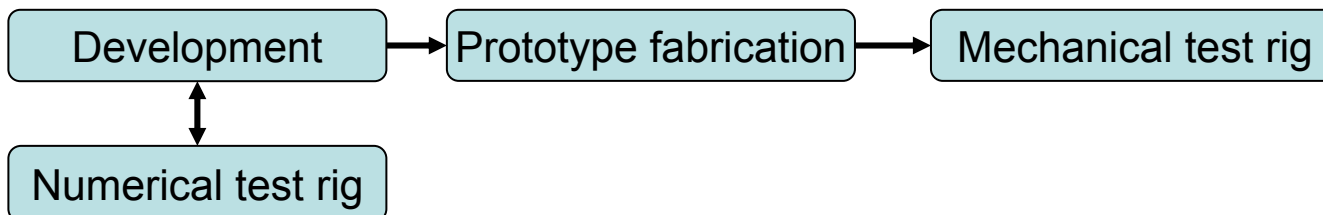
# Motivation

- FLM develops design, simulation and optimization tools to support the development process of turbo machinery
- Aim of the work performed was to prove the fitness and reliability of these tools as a numerical test rig.
  - given pump geometry of a specific user
  - “blind test”
- Introduce CFD simulation tools into the design process.

“classical” design approach



CAE-based design approach





# IDS

## IDS Integrated Design System

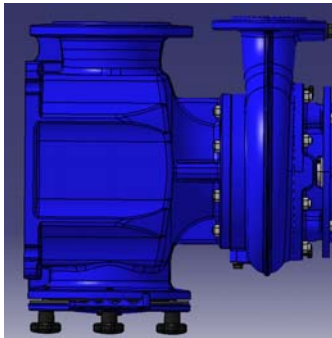
### Features:

- Geometry tools
- “automatic” grid generator
- Several solvers
- “single click” post processing unit
- Automatic run system
- Block structured grids are needed

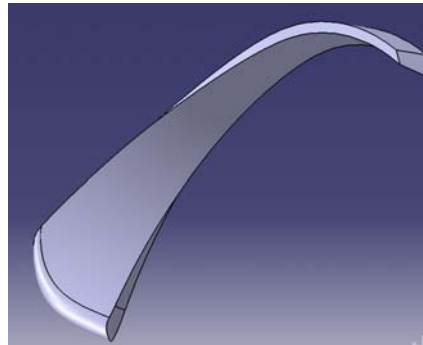
### Needed inputs:

- Geometric data from the three main parts
- Physical conditions from the fluid
- Design point data from the pump

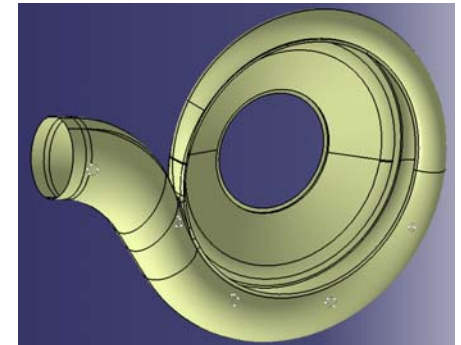
### The three main parts



Casing



Runner blade



Spiral



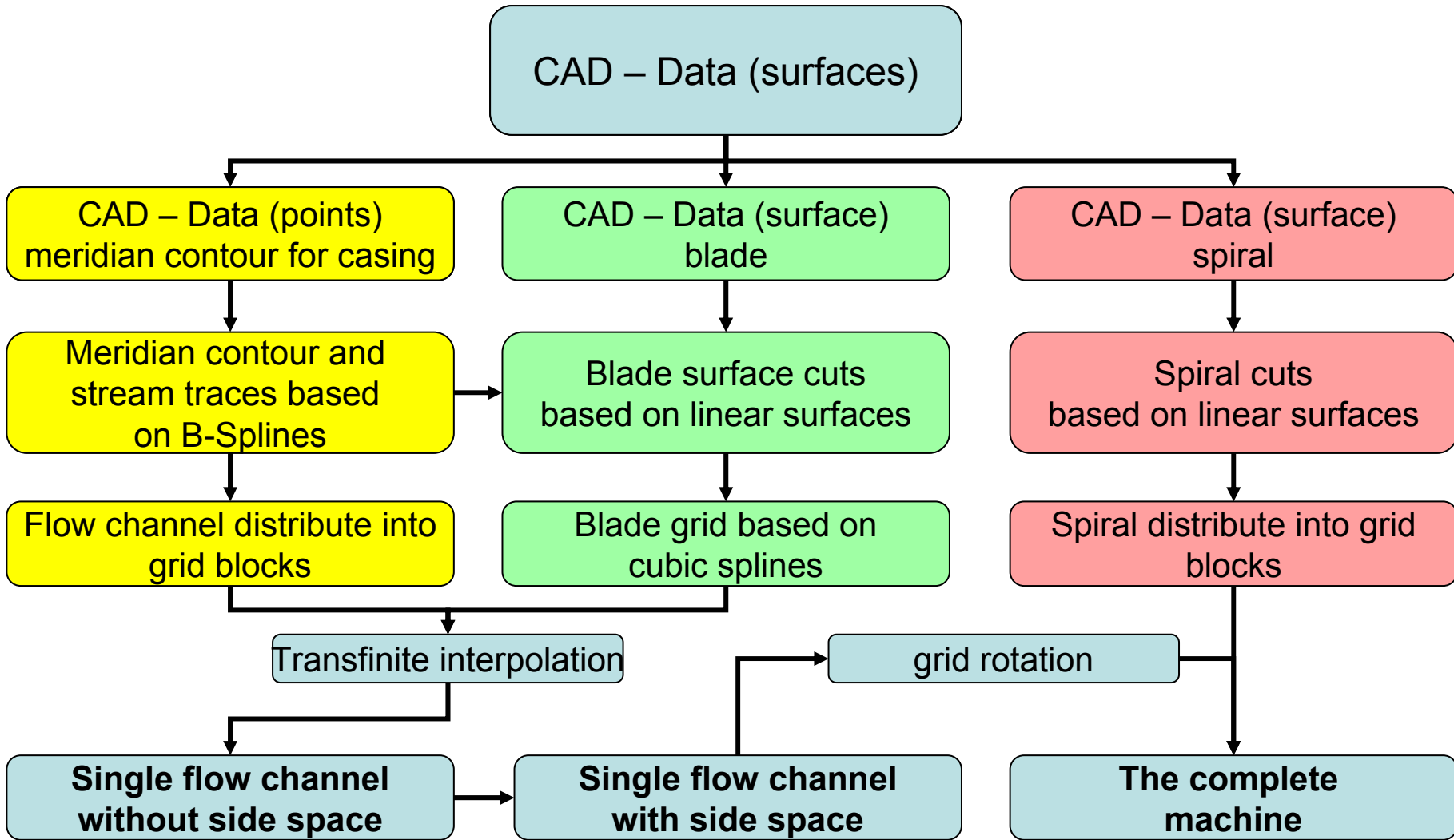
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# Geometric data

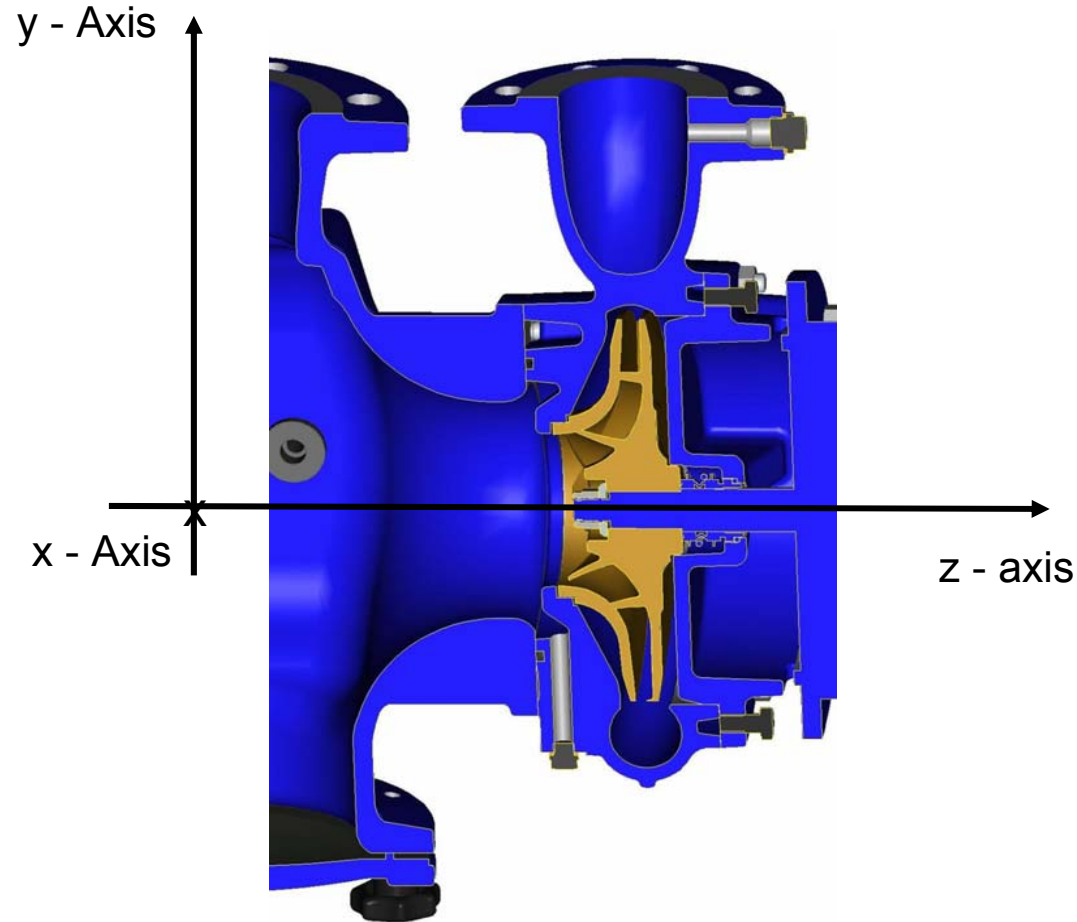




# CAD – Data from the casing (surfaces)

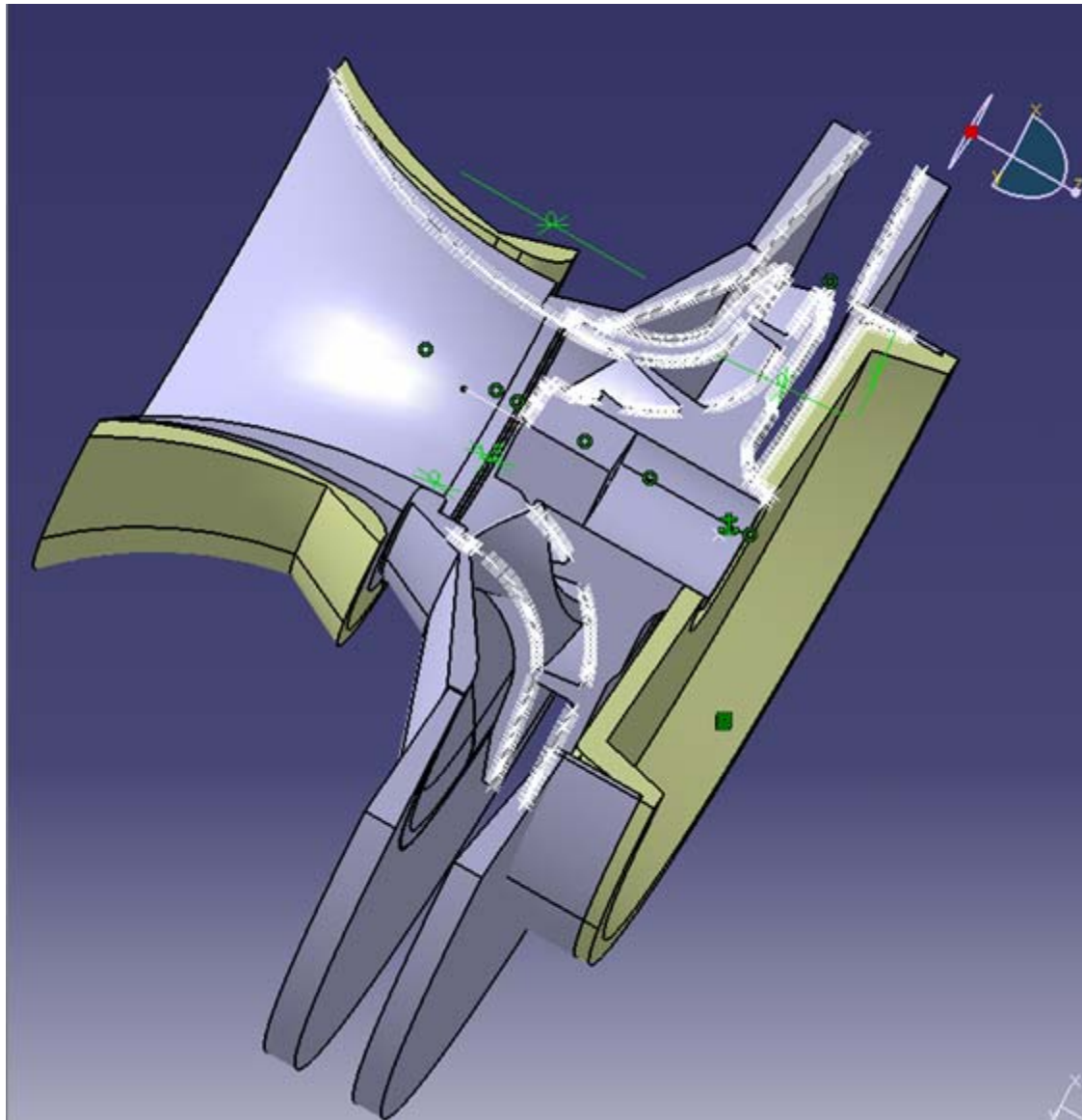
## Requirements:

- z – axis in flow direction
- rotation symmetric geometries
- absolute coordinates for every part
- rotation axis = z – axis
- measurement is meter
- distribute points along the contour
- right hand system
- CAD – Data file must be an \*.igs - file





# CATIA V5 drawing







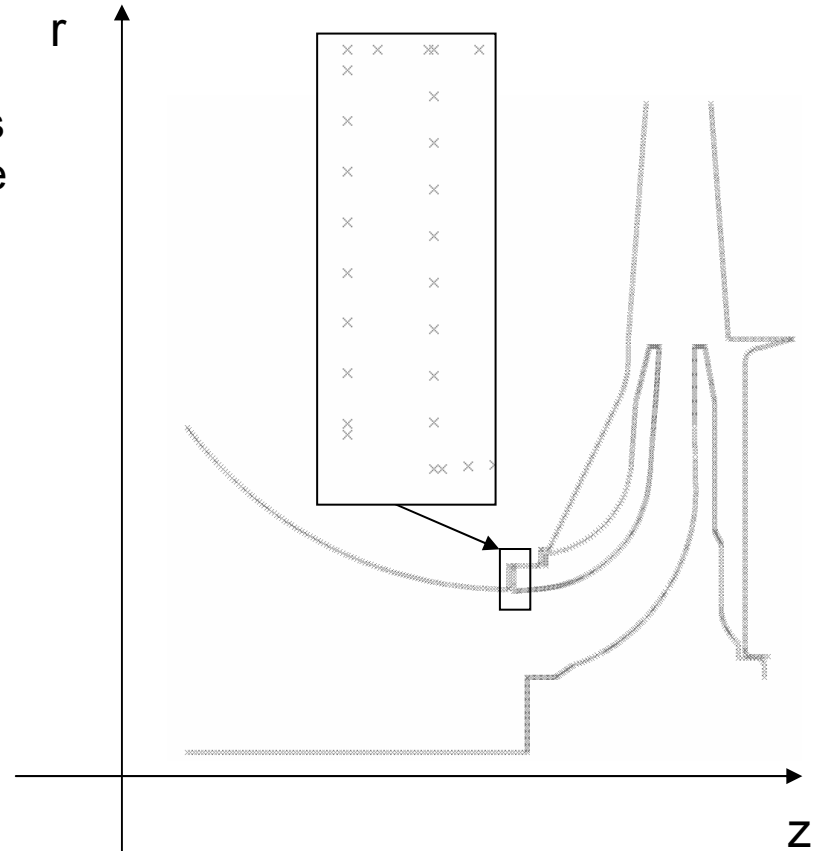
# CAD – Data meridian contour (points)

The points from CAD - data file will be transformed from  $(x, y, z)$  – coordinates into cylinder coordinates with the following rule

$$r = \sqrt{x^2 + y^2}$$

$$z = z$$

→every point has an own coordinate  $(r, z)$





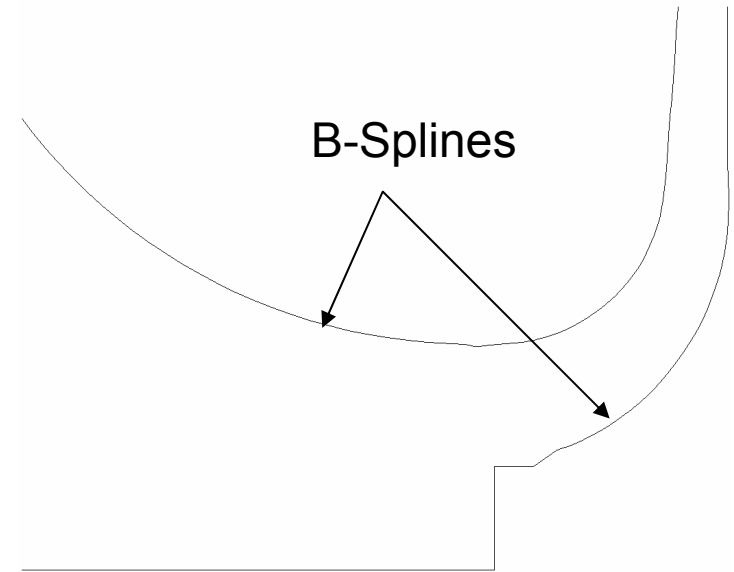
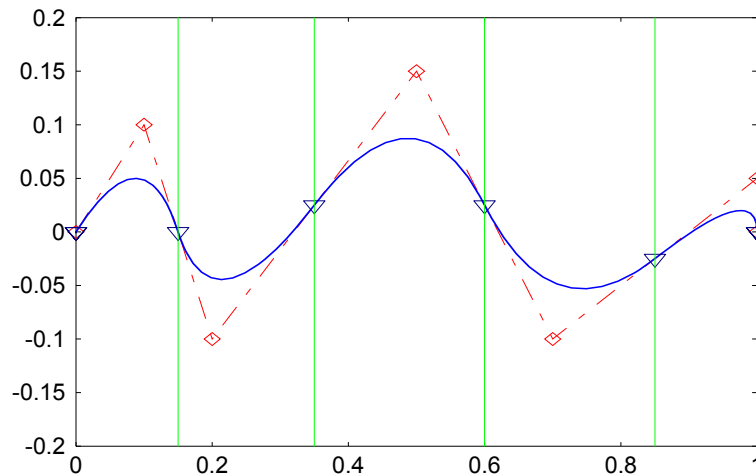
# Meridian contour and stream traces based on B-Splines

## Uniform B-Spline:

order	$k = 3$
Descriptor points	$n = 7$
⇒ support vector elements	$l = n + k = 10$
⇒ inner knots	$IK = l - 2k = 4$
⇒ sections	$p = IK + 1 = 5$

## Support vector T:

$T = T(0, 0, 0, 0.2, 0.4, 0.6, 0.8, 1.0, 1.0, 1.0)$



## Recursive Formula

$$N_{i,k}(t) = \frac{(t - t_i)N_{i,k-1}(t)}{t_{i+k-1} - t_i} + \frac{(t_{i+k} - t)N_{i+1,k-1}(t)}{t_{i+k} - t_{i+1}}$$

$$N_{i,1}(t) = \begin{cases} 1 & \text{für } t_i \leq t < t_{i+1} \\ 0 & \text{sonst} \end{cases}$$

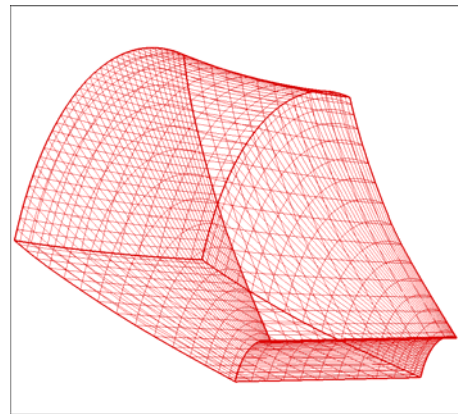
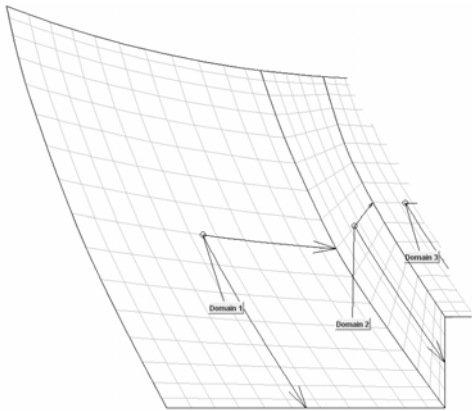
$t_i$ : Knot, elements of the support vector T  
 $t$ : Curve parameter



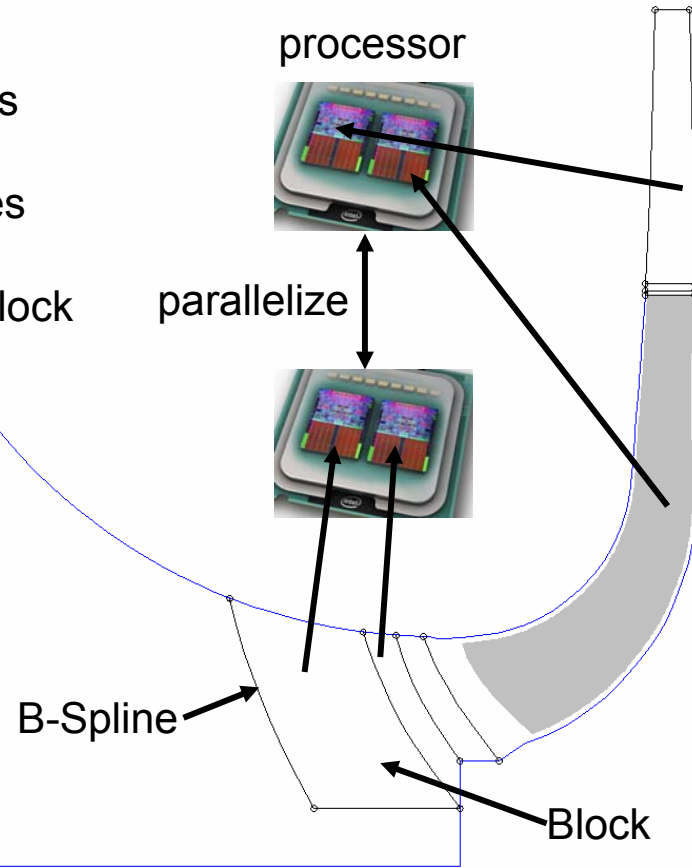
# Flow channel distribute into grid blocks

## Grid – blocks:

- distribute the flow channel into calculation areas
- block boundaries consists of B-Splines and lines
- grid size can be adapted individually to every block



Grid generation with transfinite interpolation





# CAD – Data (surface) Blade

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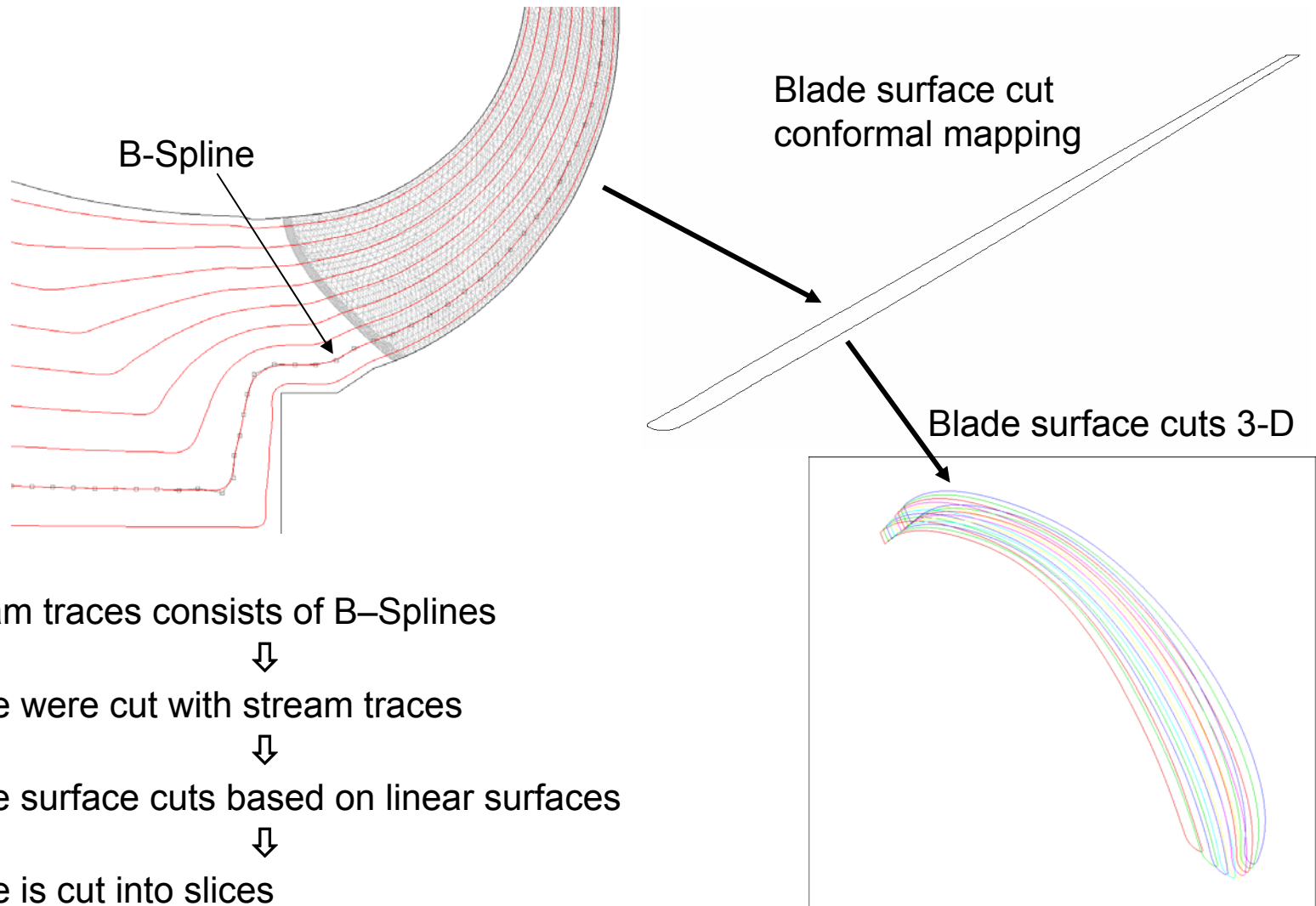
## Requirements:

- positive rotation around the z – axis
- the positioning coordinates must fits into the meridian contour
- CAD – Data file must be a \*.stl – file





# Blade surface cuts based on linear surfaces



stream traces consists of B-Splines



blade were cut with stream traces



blade surface cuts based on linear surfaces



blade is cut into slices



# Blade grid based on cubic splines

## Interpolating the cuts with cubic splines

Cubic parabola

$$f_i(x) = a_i x^3 + b_i x^2 + c_i x + d_i$$

i: Section number

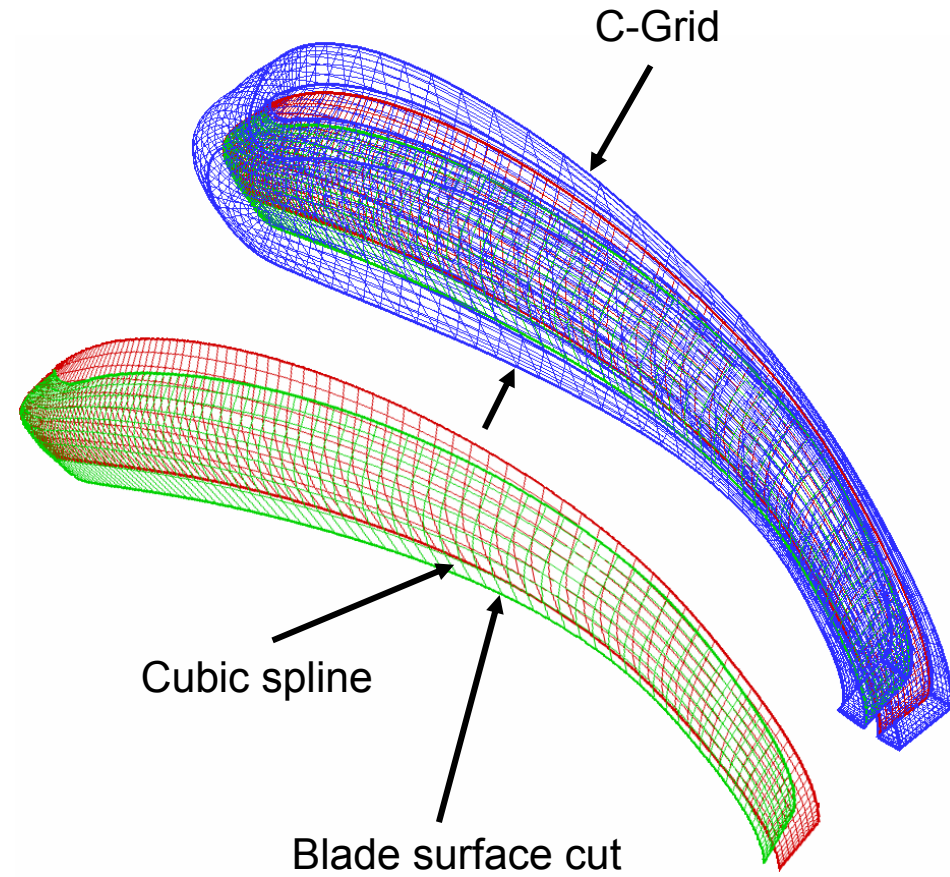
Number of unknown = 4 \* number of sections

Number of Nodes = number of sections + 1

$$f_1(x_k) = f_2(x_k)$$

$$\frac{dy_1}{dx_k} = \frac{dy_2}{dx_k}$$

$$\frac{d^2 y_1}{dx_k^2} = \frac{d^2 y_2}{dx_k^2}$$

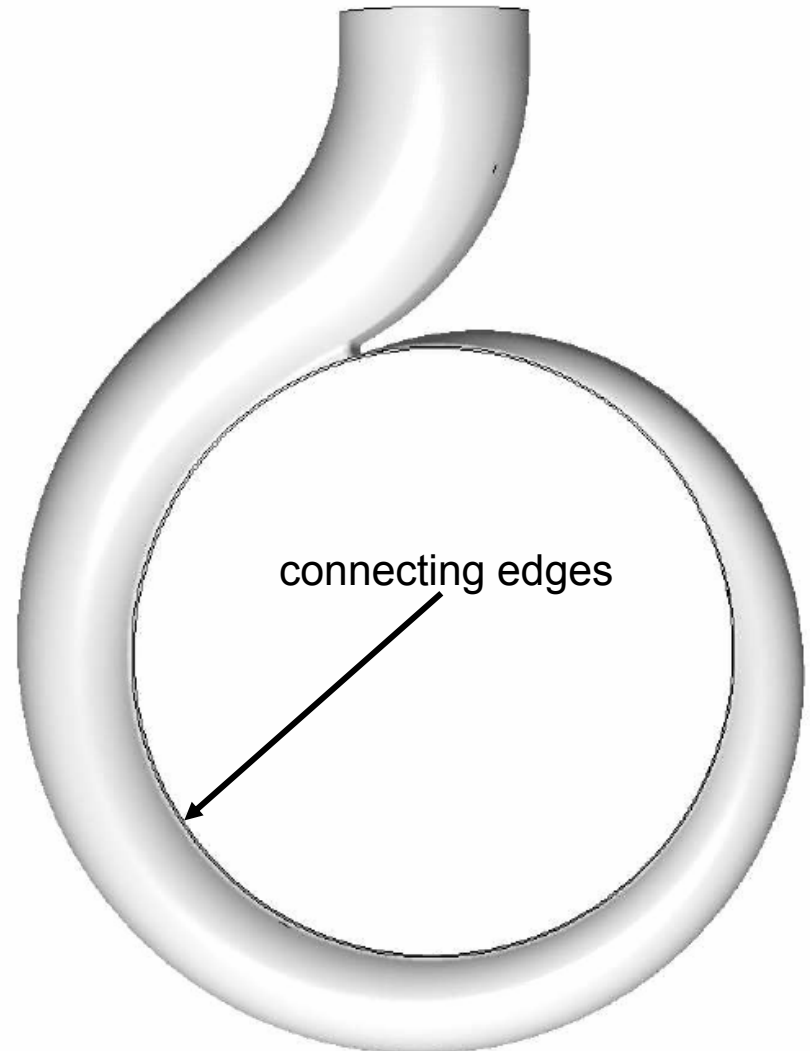




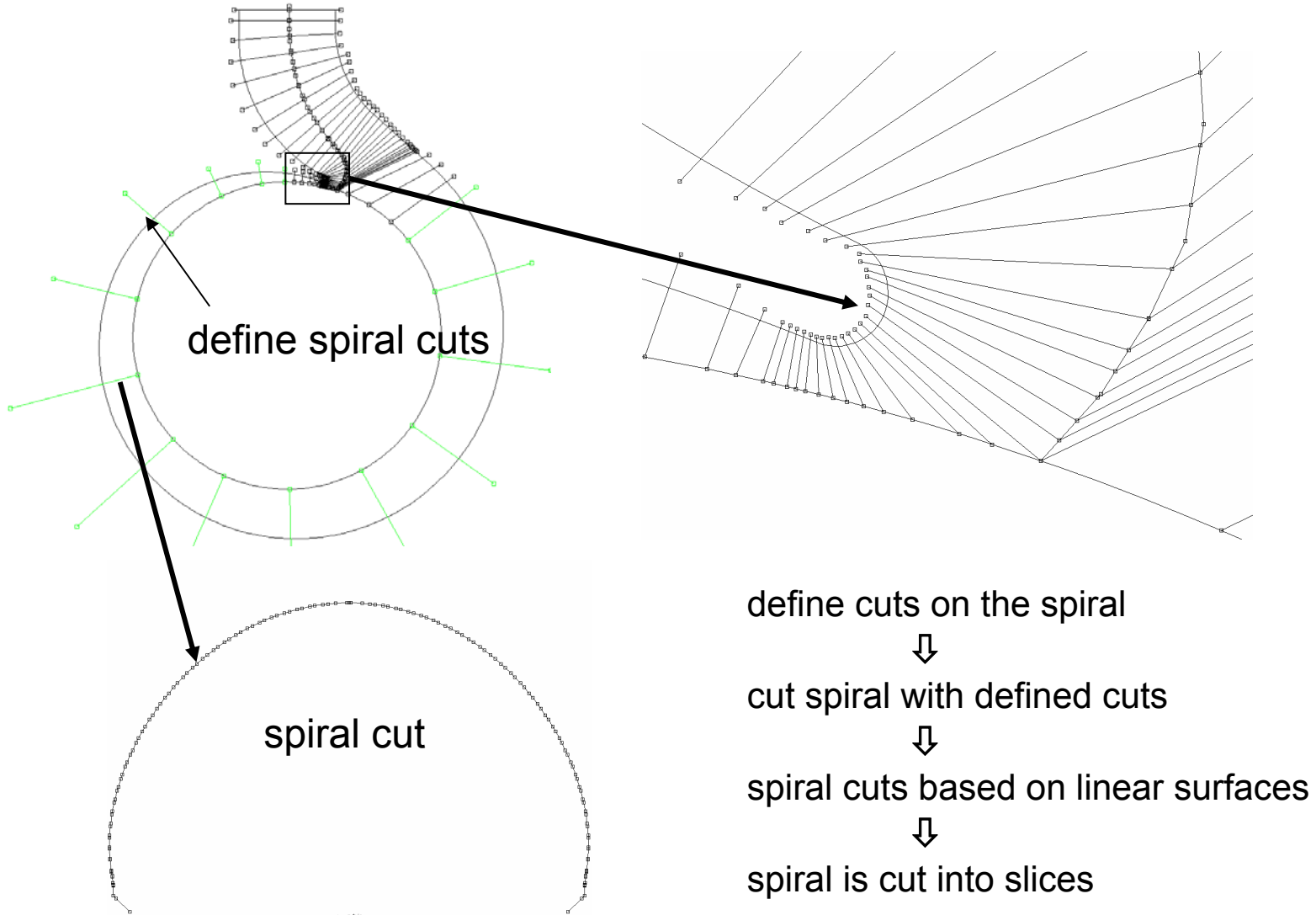
# CAD – Data (surface) spiral

## Requirements:

- positive rotation around the z – axis
- the positioning coordinates must fit to the exhaust from the pump
- the two connecting edges must be planar, parallel to each other and concentric to the origin
- the measurement is meter
- CAD – Data file must be a \*.stl – file

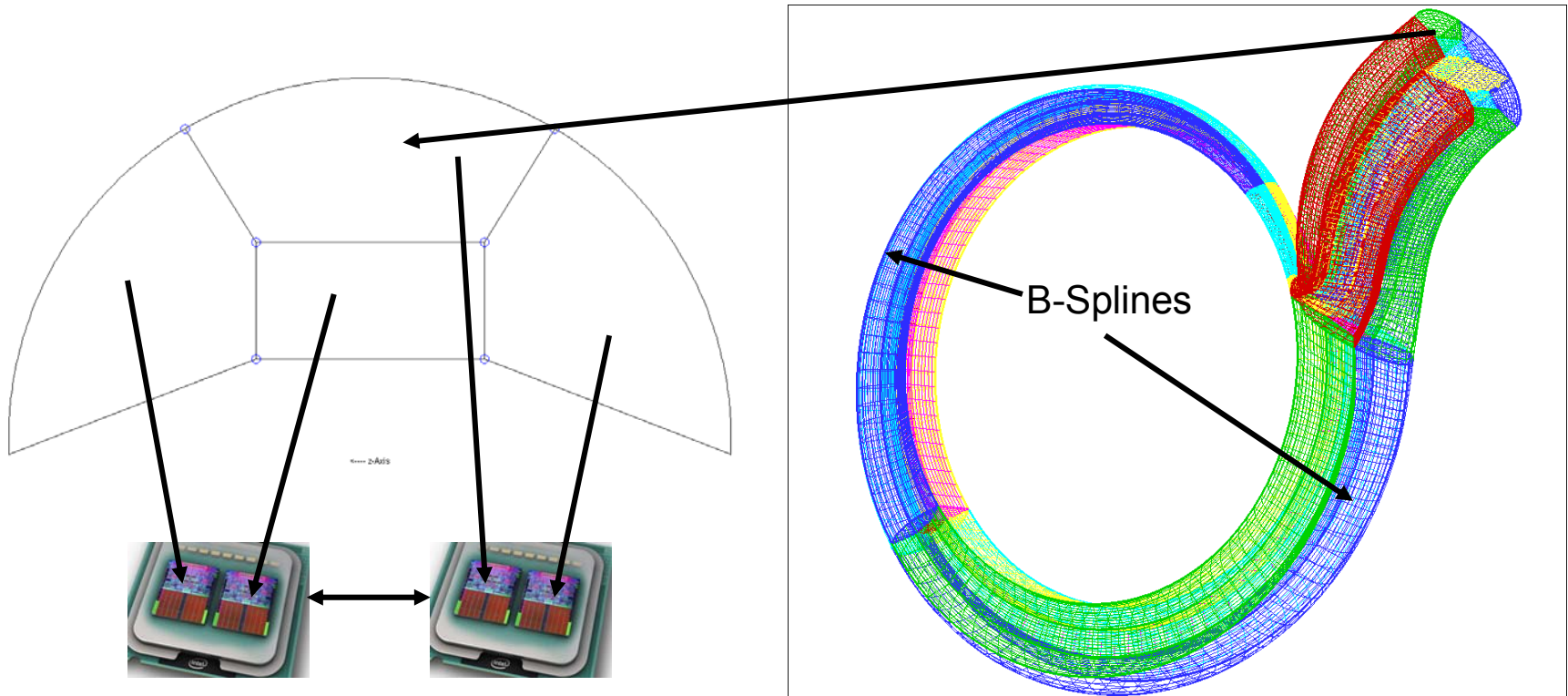


# Spiral cuts based on linear surfaces





# Spiral segmentation into grid blocks



## Spiral blocks:

- calculation areas segment the flow channel
- lines in peripheral and radial direction consists of B-Splines
- complete spiral can be meshed with hexahedrons



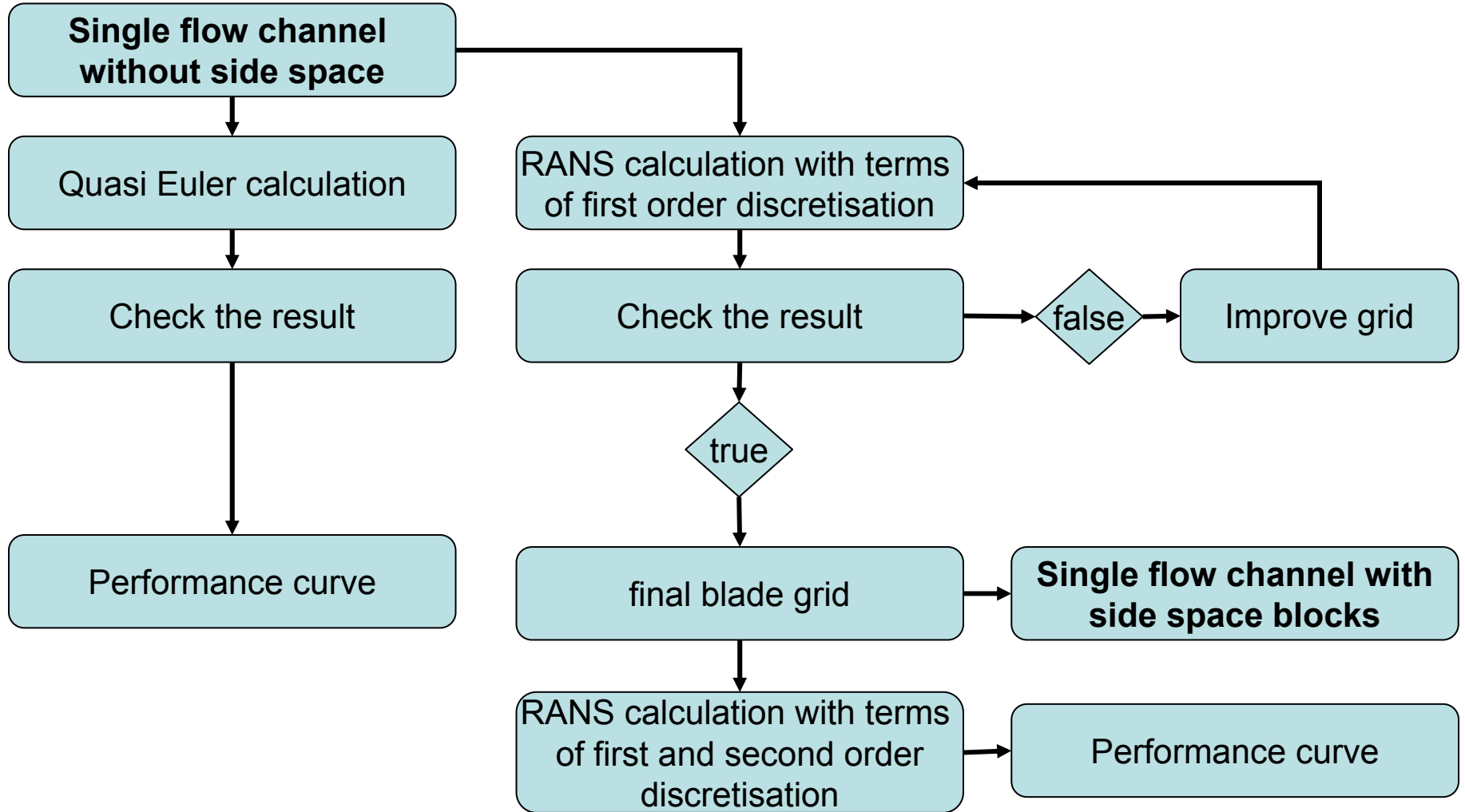
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# Single flow channel without side space





# Single – flow channel without side space

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- Quasi Euler calculation for approximation
- RANS calculation with terms of first and second order discretisation
- Simplified outlet model
- Blade grid optimization
- Performance curves for operation characteristics
- Reference for further simulations

## Inputs:

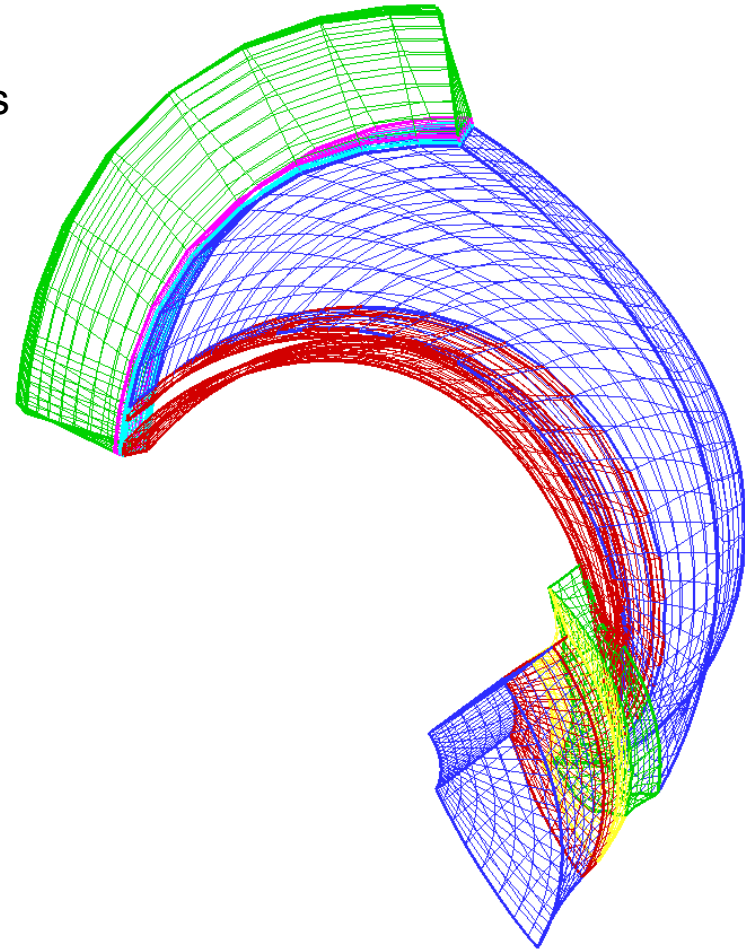
- Rotation frequency  $\omega$
- Volume flow  $\dot{V}$
- Reference radius  $r_{ref}$
- Density of fluid  $\rho$
- Viscosity  $\nu$
- Turbulence parameters  $(k, \varepsilon)$
- Number of blades

$$k = 1,5 \cdot (Tu \cdot c_{inlet})^2 \quad c_{inlet} = \frac{\dot{V}}{A_{inlet}}$$
$$\varepsilon = C_{\mu}^{0,75} \frac{k^{1,5}}{l_{char}} \quad C_{\mu} = 0,09 \quad l_{char} \cong 0,07 r_{ref}$$



# Quasi Euler calculation

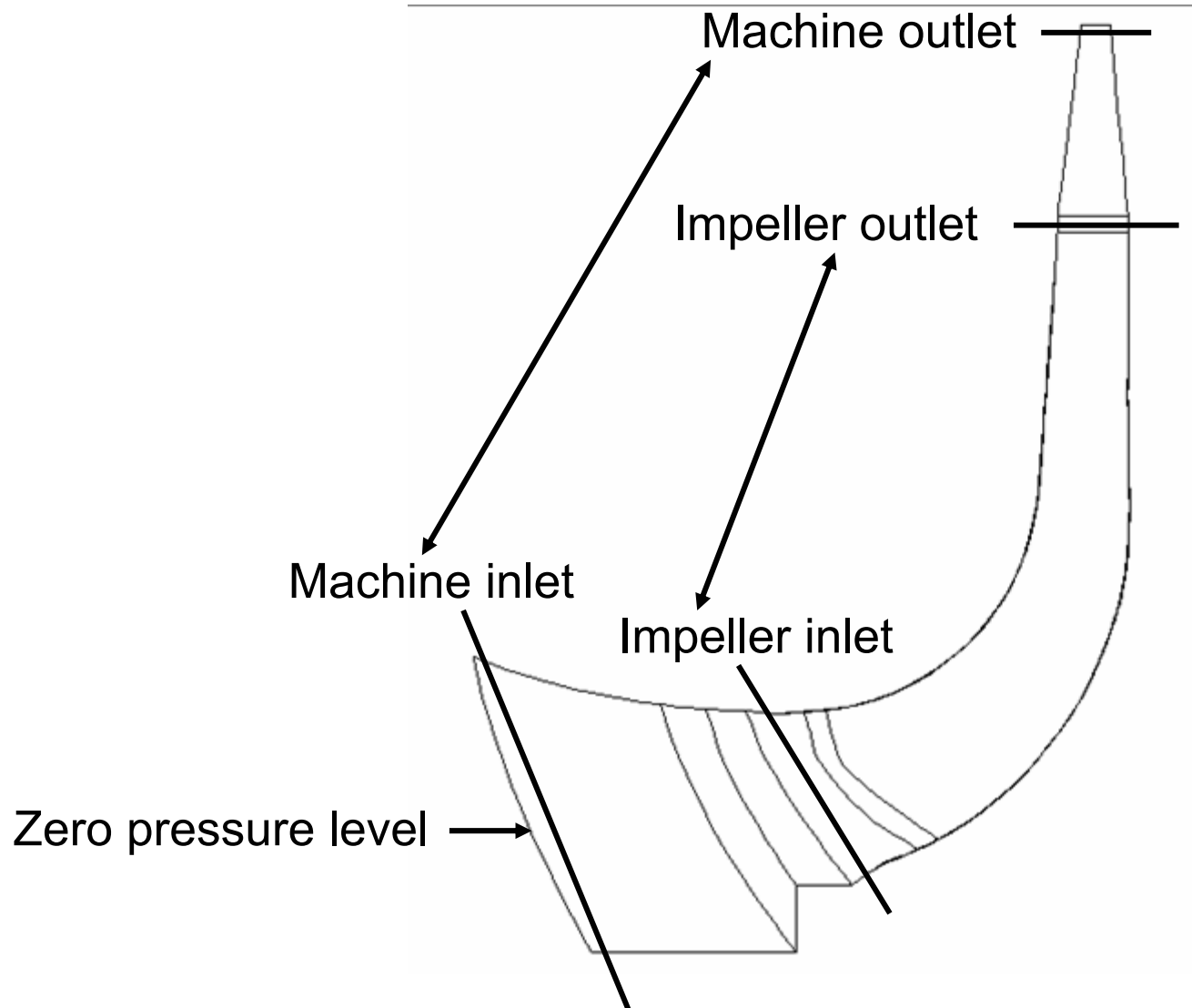
- grid with large cells  $\Rightarrow$  low number of nodes
- no wall friction
- no turbulence model
- adjusted viscosity
- fast and simple calculation
- rough result
- first approximation of performance



9522 Nodes

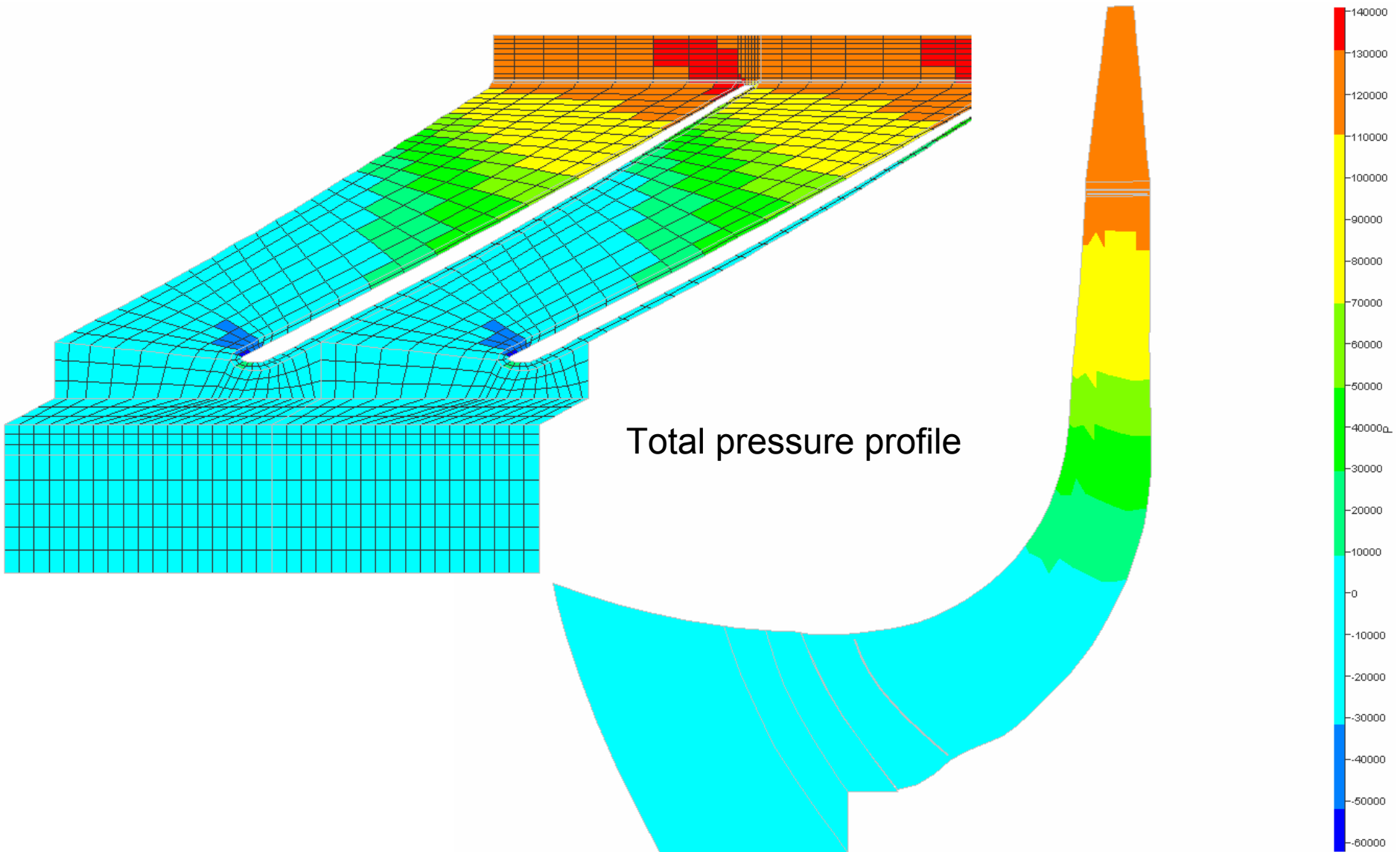


# Measurement positions, balancing





# Result of a quasi Euler calculation

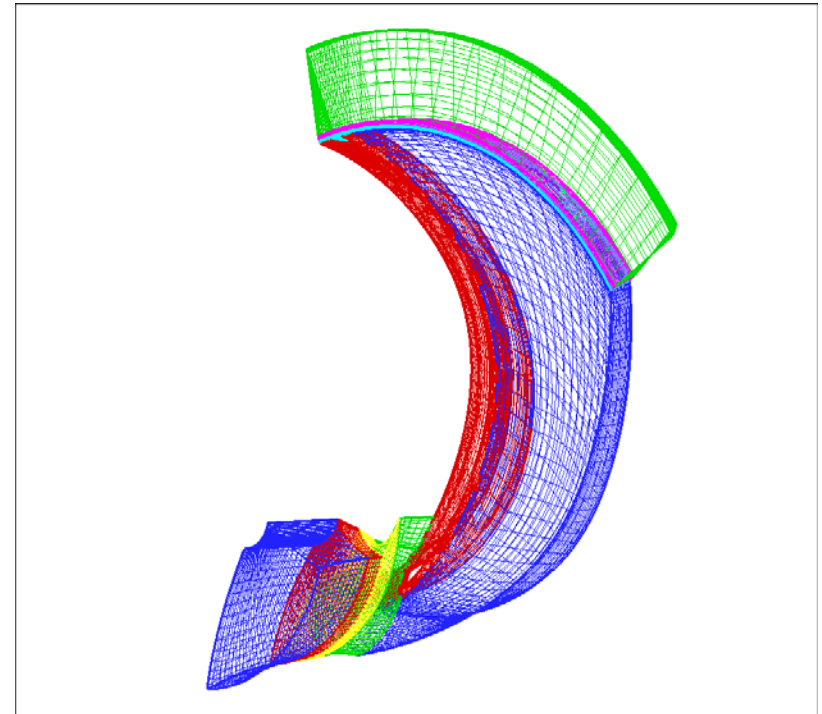


Total pressure profile



# RANS calculation with wall friction

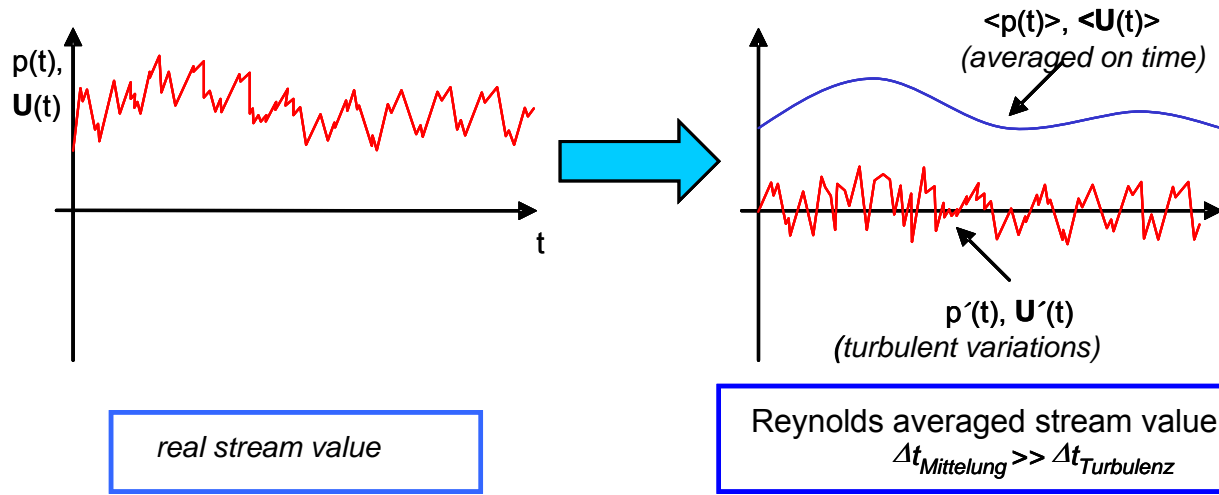
- fine grid  $\Rightarrow$  increased number of nodes
- simplified outlet model
- $k, \varepsilon$  – turbulence model
- precise result
- no cavitation effects
- wall friction
- calculation with terms of first and second order discretisation
- final blade grid



about 54000 nodes



# Reynolds averaged turbulence model



$$U(t) = \bar{u}_1 + \bar{u}_2 + \bar{u}_3$$

$$k = \frac{1}{2} \left\{ \bar{u}_1^2 + \bar{u}_2^2 + \bar{u}_3^2 \right\}$$

$$\nu_t = c_\mu \cdot \frac{k^2}{\varepsilon}$$

$$c_\mu = 0.09$$

$u$  = velocity [m/s]

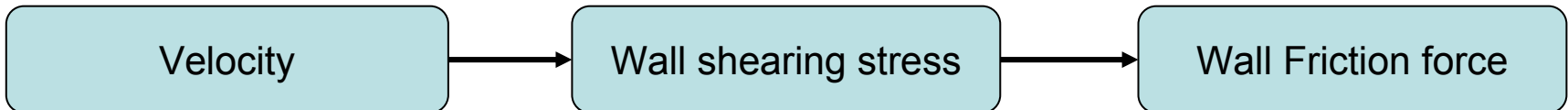
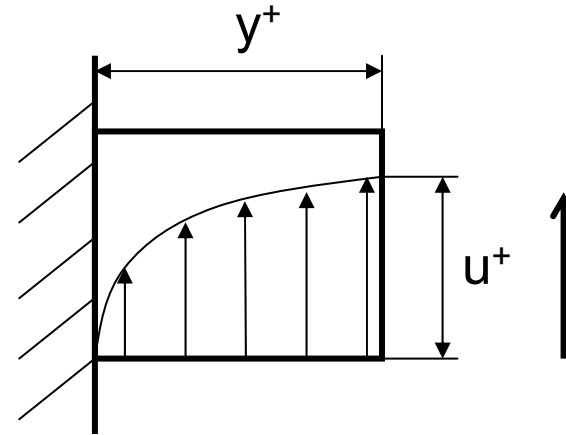
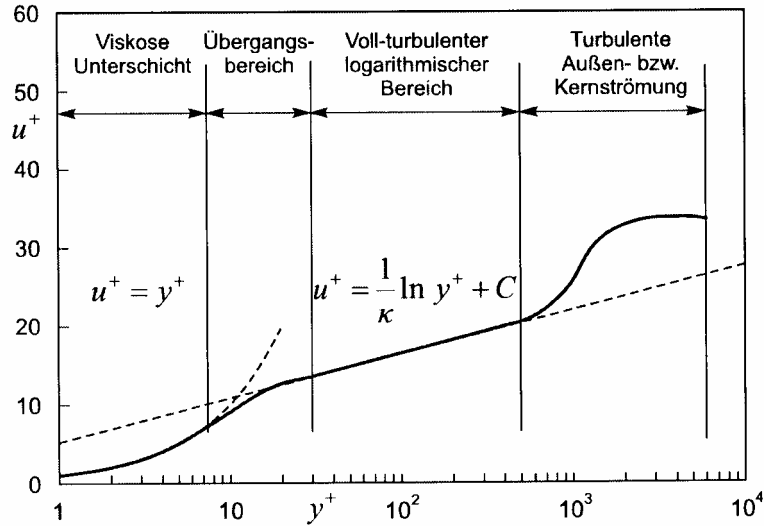
$\nu_t$  = turbulent viscosity [ $\text{m}^2/\text{s}$ ]

$\varepsilon$  = dissipation rate [ $\text{m}^2/\text{s}^3$ ]

$k$  = turbulent kinetic energy [ $\text{m}^2/\text{s}^2$ ]

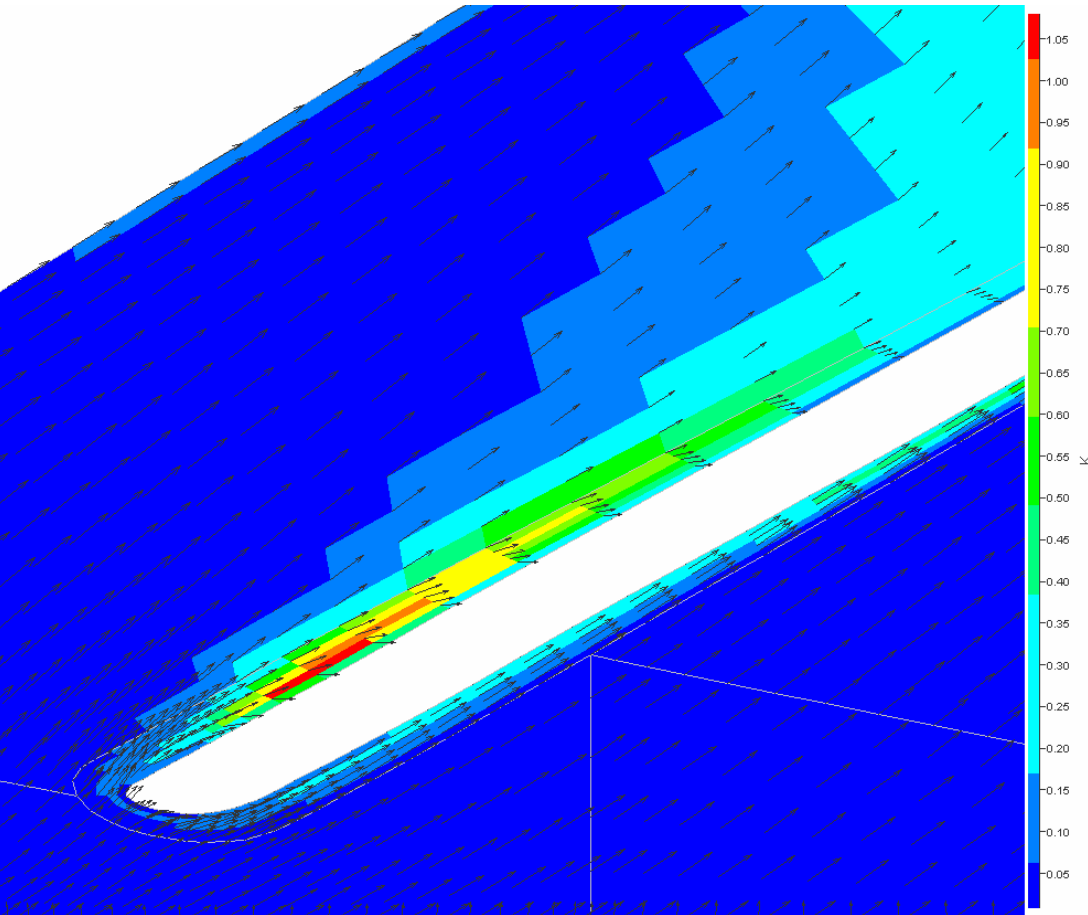


# Wall friction model

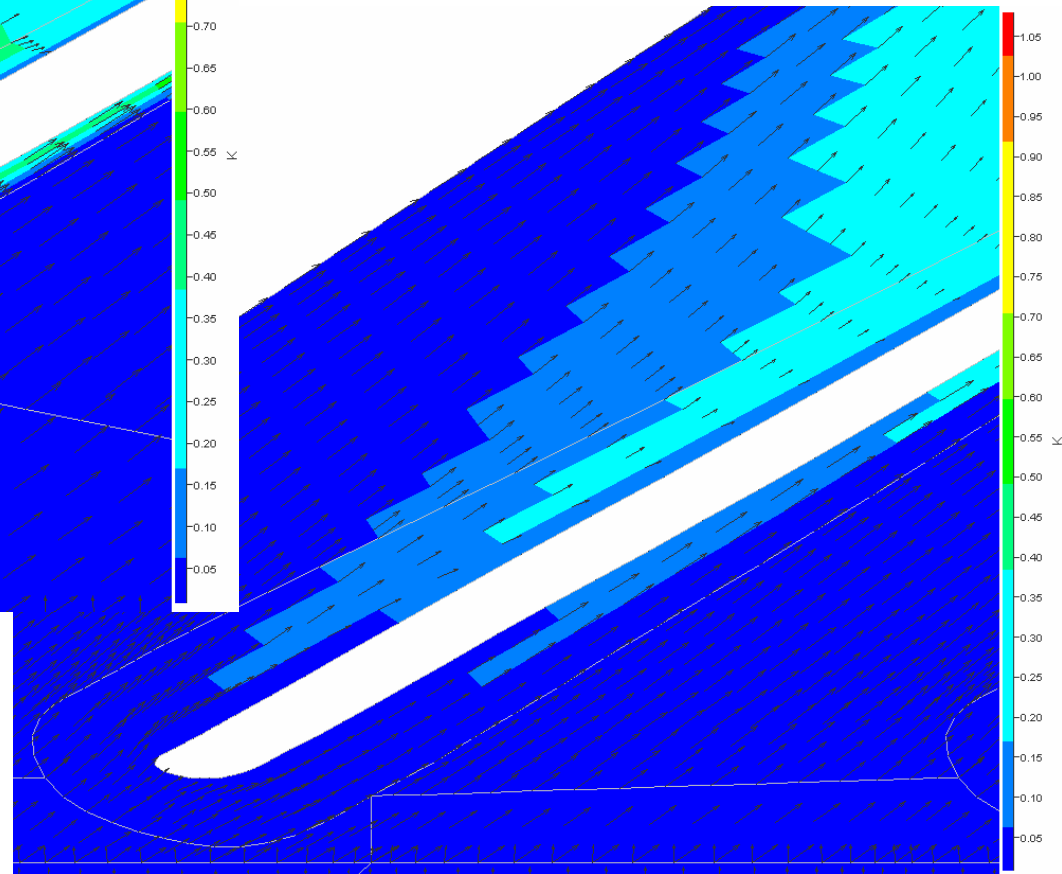




# Evaluation of wall function



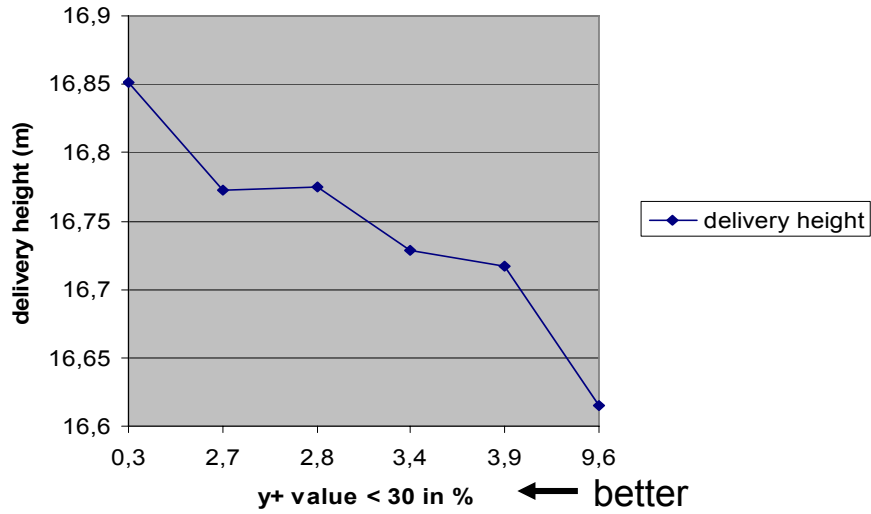
Turbulent kinetic energy



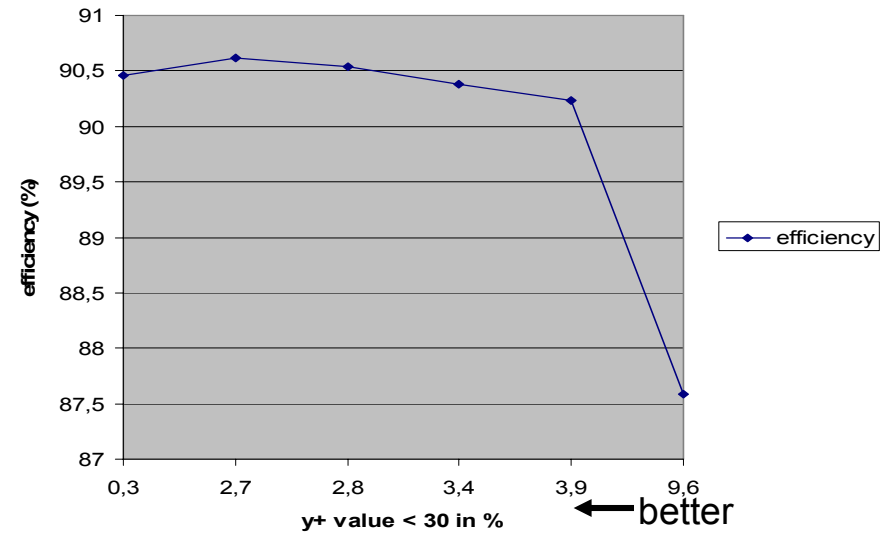


# Evaluation of wall function

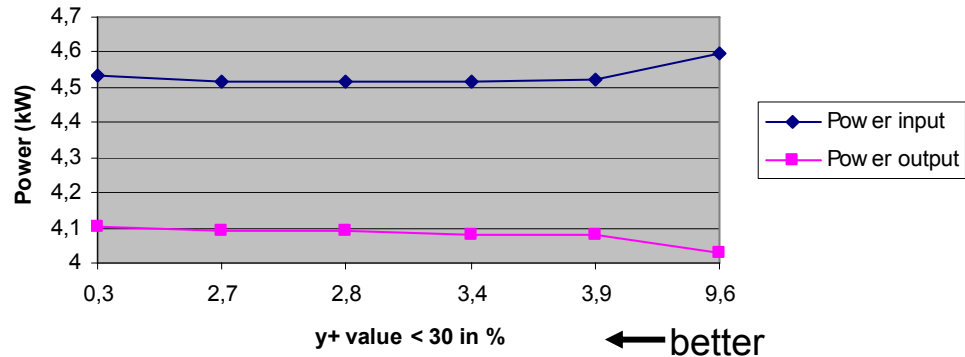
## delivery height



## efficiency



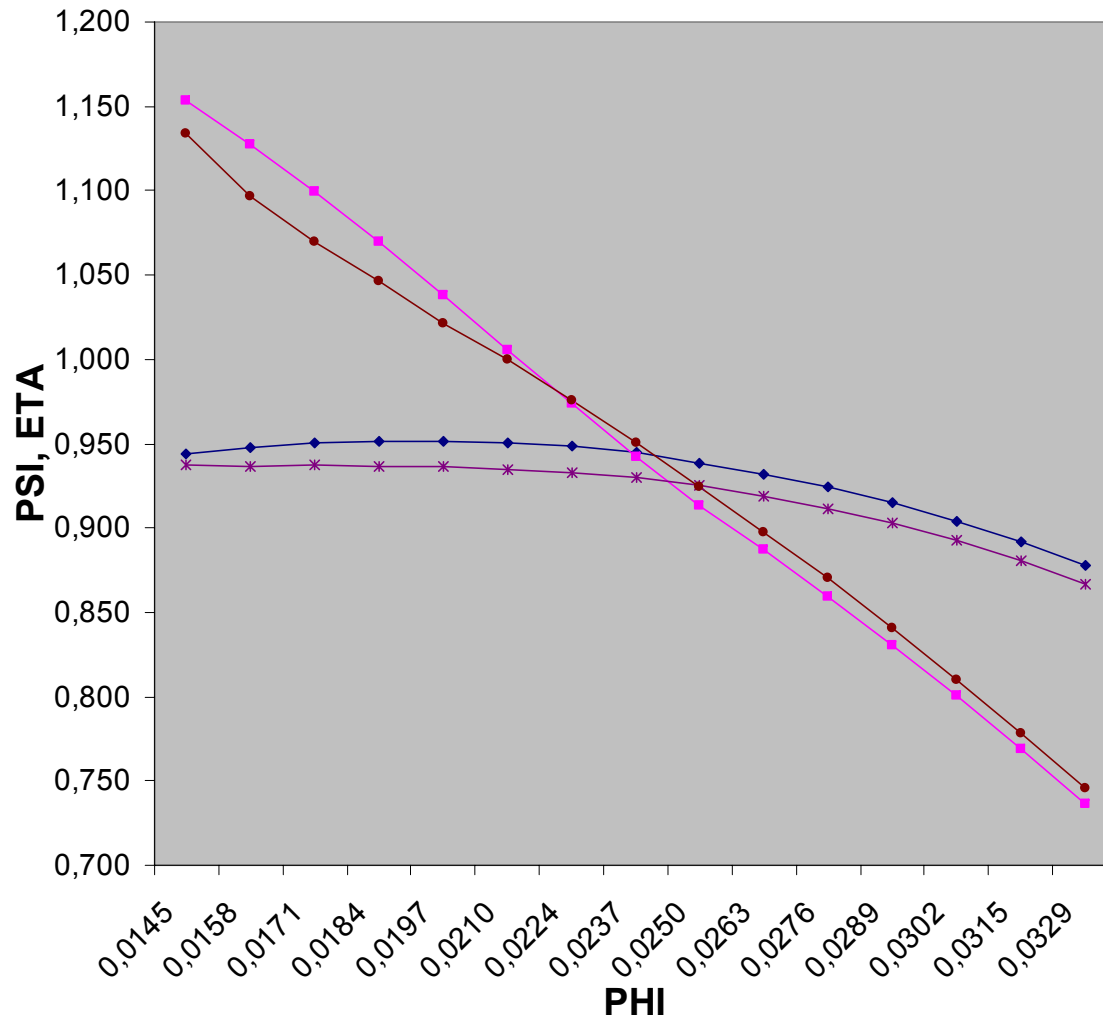
## Power





# Comparison of results

## Single Flow Performance Curve



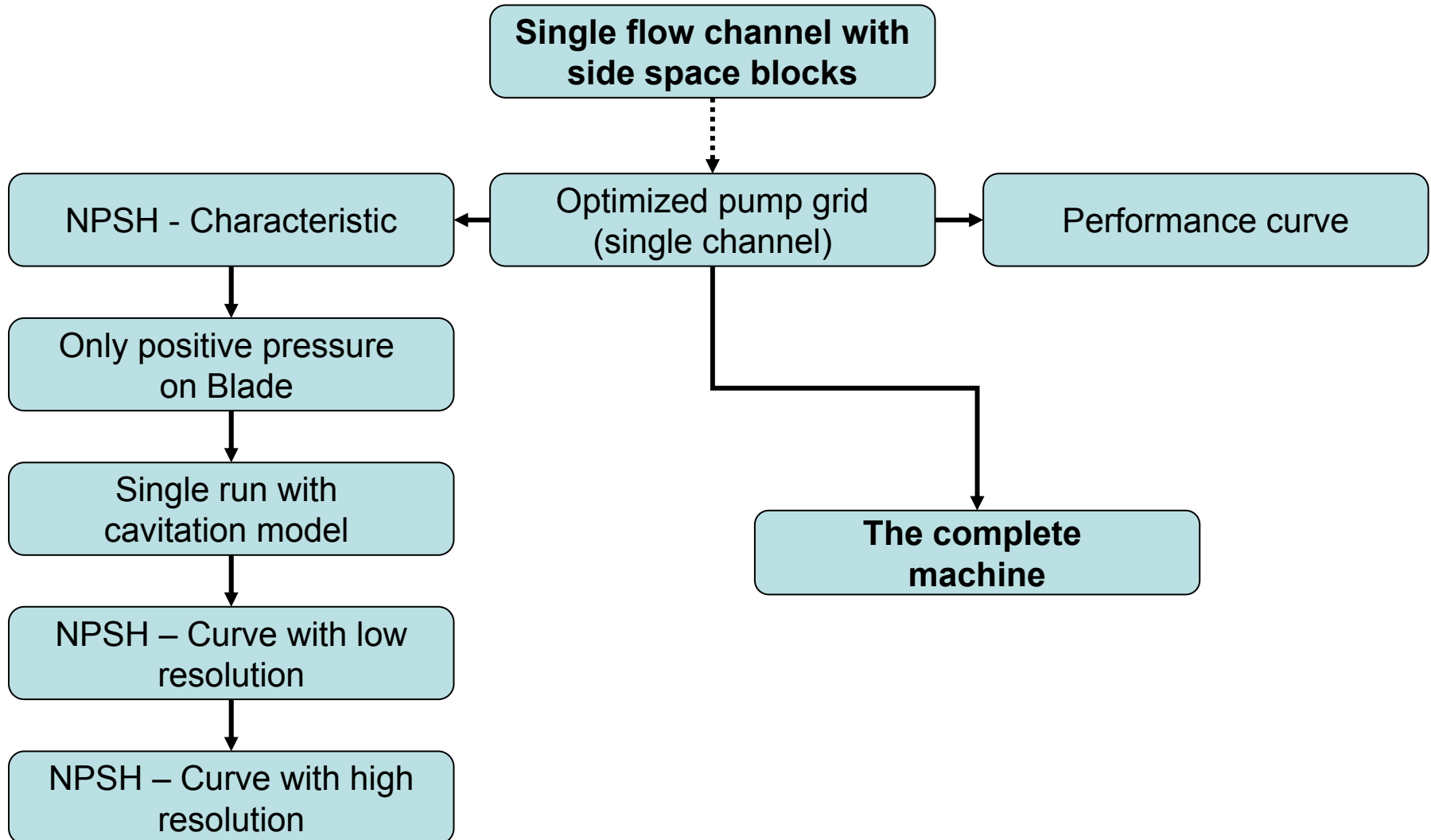
$$\varphi = \frac{Q}{r_{ref}^2 \cdot \pi \cdot u_{ref}}$$

$$\Psi_t = \frac{2 \cdot \Delta p_t}{\rho \cdot u_{ref}^2}$$

- ETA Euler 9 ST
- delta PSI total Euler 9 ST
- ETA RANS 15 ST
- delta PSI total RANS 15 ST



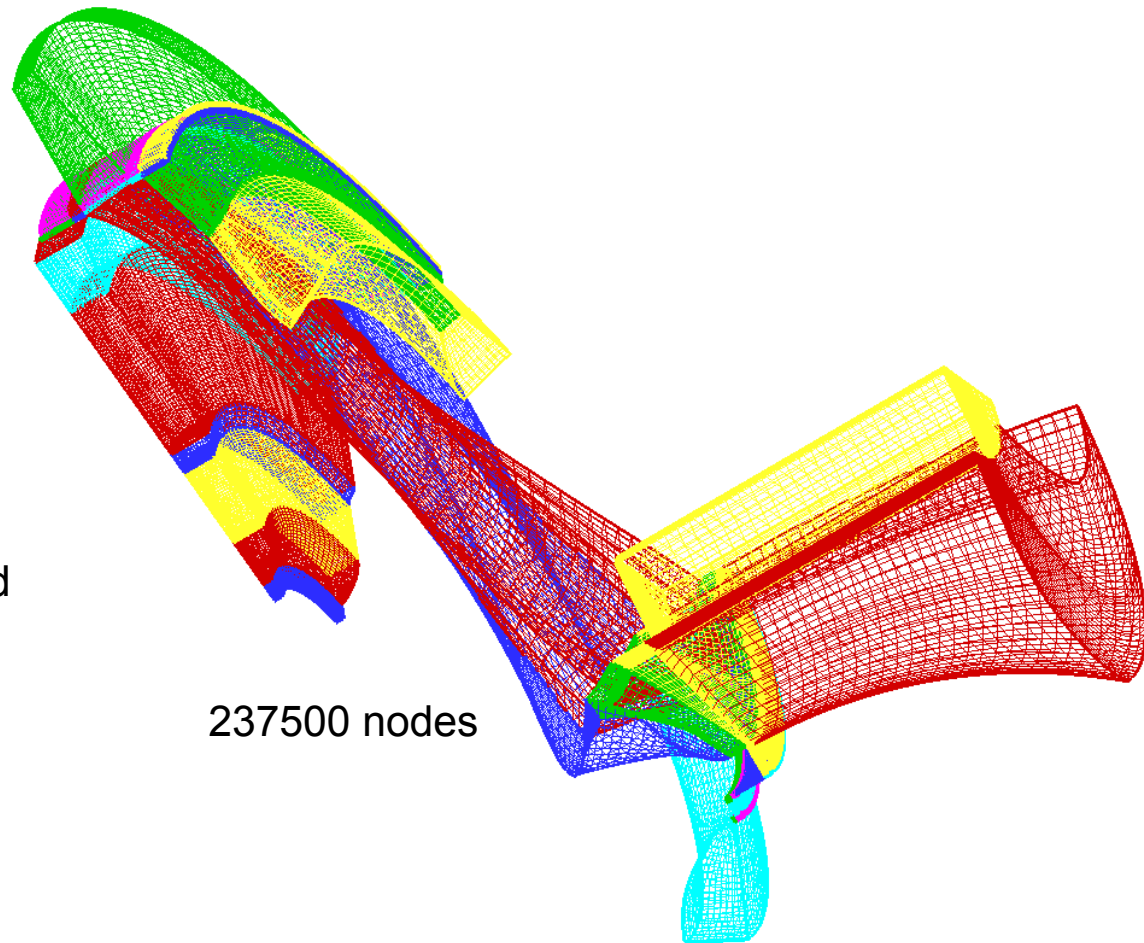
# Single flow channel with side space





# Single flow channel with side space blocks

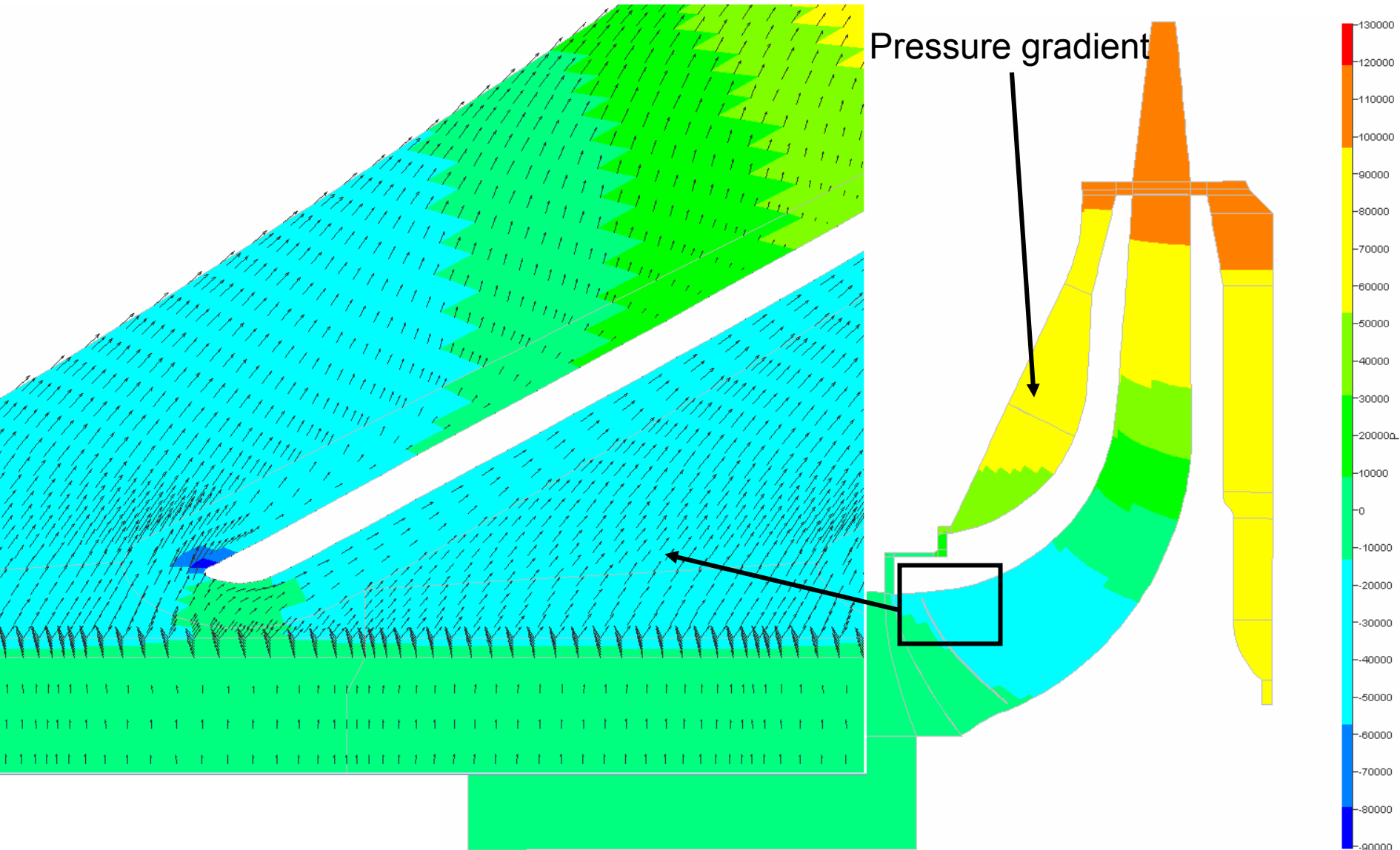
- fine grid  $\Rightarrow$  large number of nodes
- simple outlet
- k,  $\epsilon$  – turbulence model
- precise result
- no cavitation
- wall friction
- calculation with terms of first and second order discretisation
- optimized side space grid
- reference for NPSH curve



237500 nodes



# Total pressure meridian contour

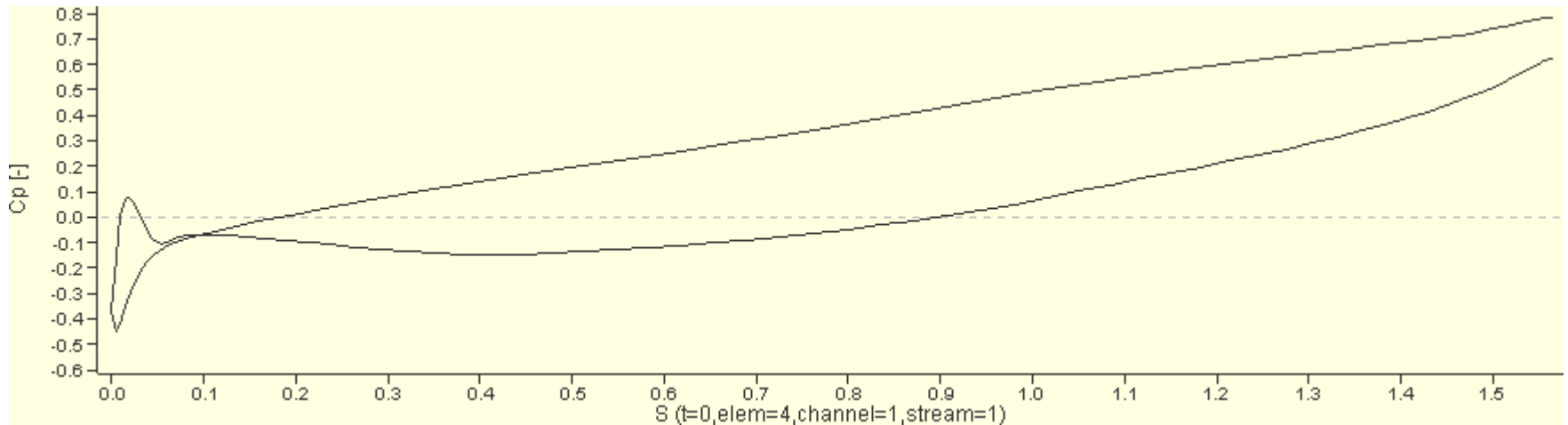




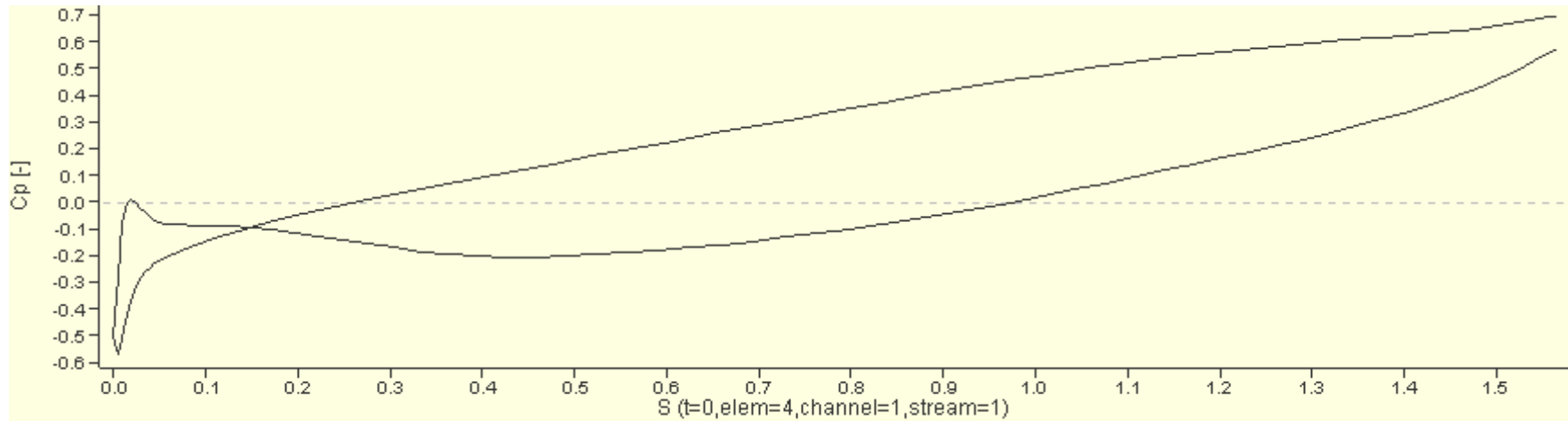


# Pressure profile on blade

Pressure profile on blade without side space

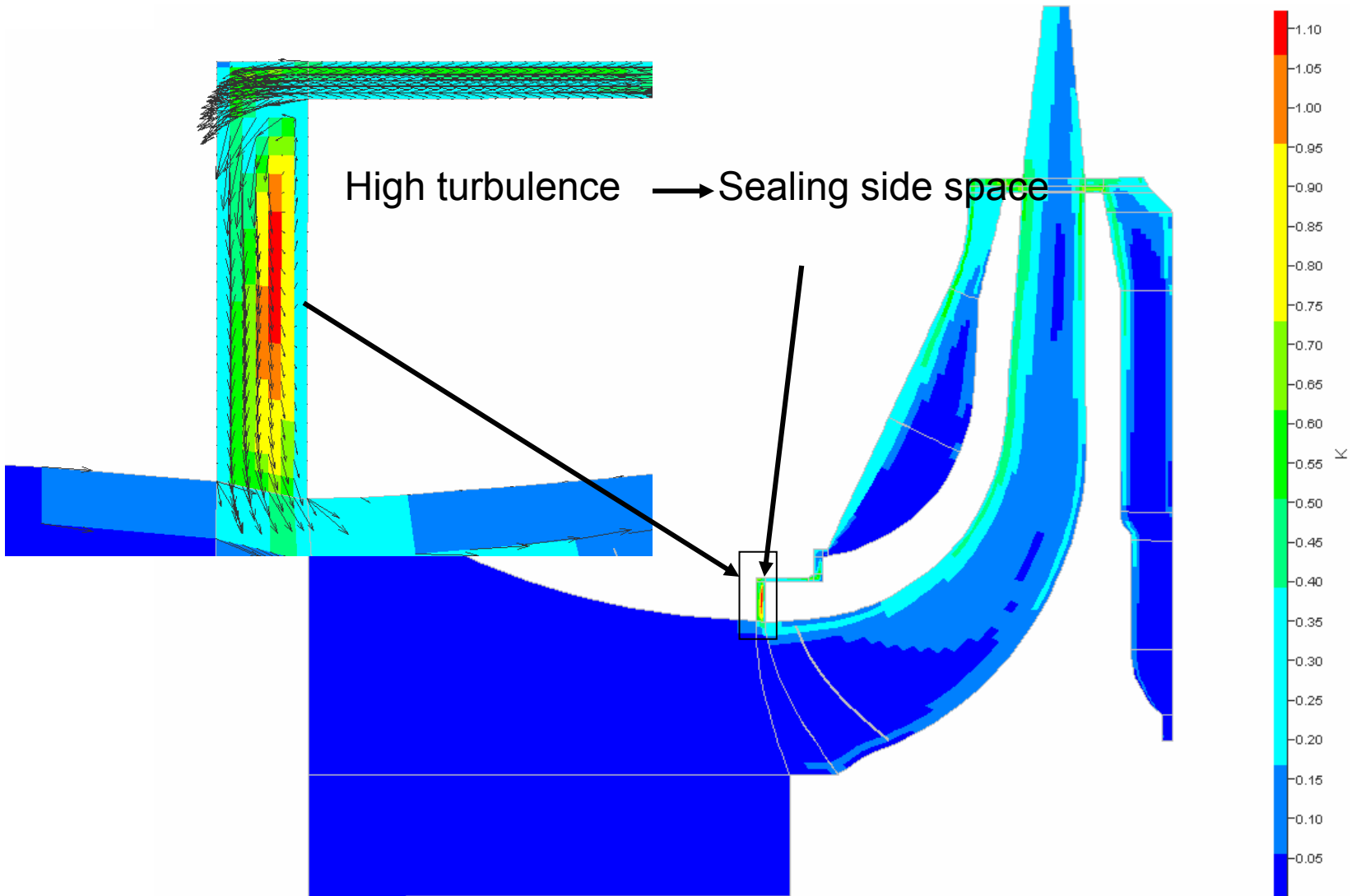


Pressure profile on blade with side space





# Turbulent kinetic energy meridian contour



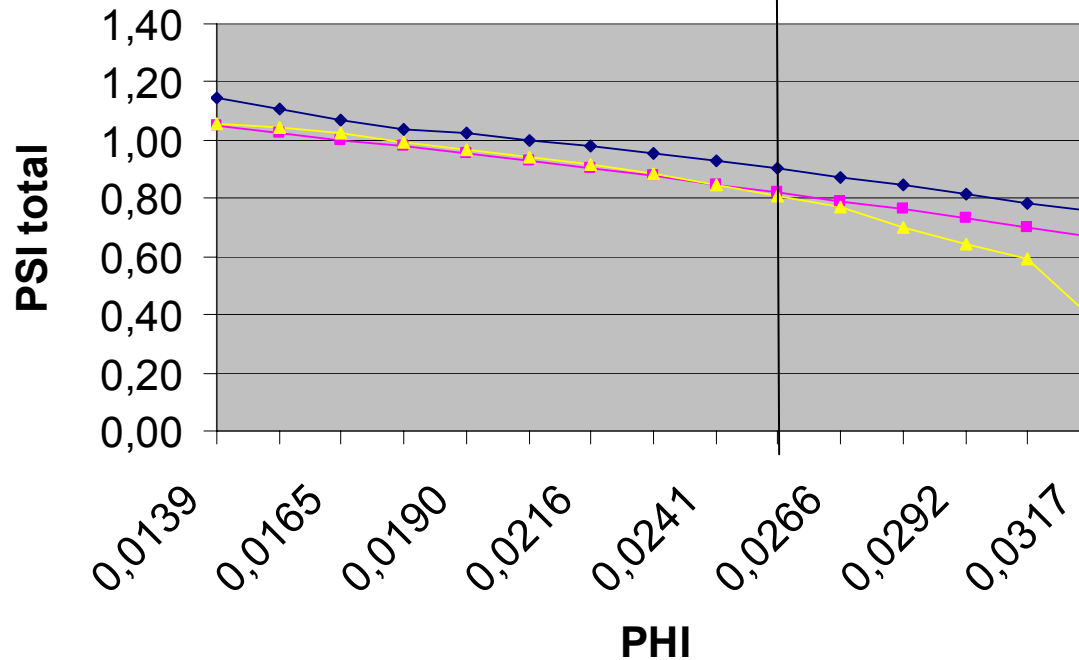


# Comparison of results

### Dimesionless total pressure

$$\varphi = \frac{Q}{r_{ref}^2 \cdot \pi \cdot u_{ref}}$$

$$\Psi_t = \frac{2 \cdot \Delta p_t}{\rho \cdot u_{ref}^2}$$



- ◆— delta PSI total without bypass
- delta PSI total with bypass
- ▲— delta PSI total machine



# NPSH - Characteristic

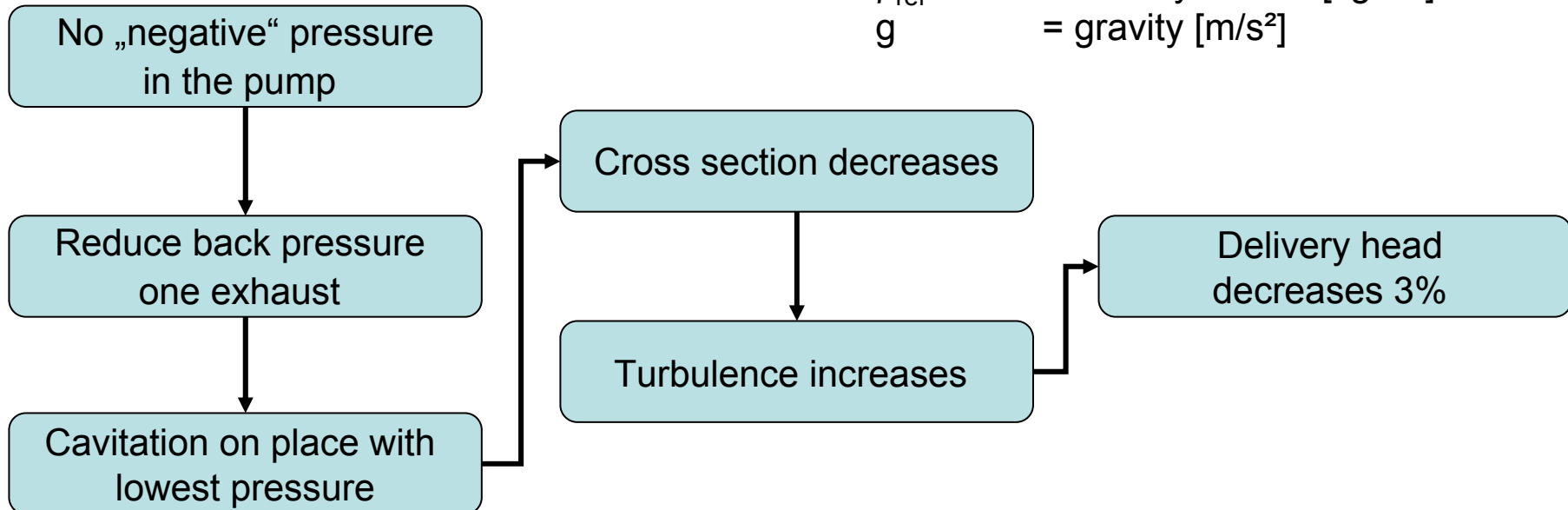
NPSH **N**et **P**ositive **S**uction **H**ead

- Single flow channel with side space
- Cavitation model (volume fraction based)
- Back pressure on exhaust

$$NPSH = \frac{P_{t,inlet} - P_{vapor}}{\rho_{ref} \cdot g}$$

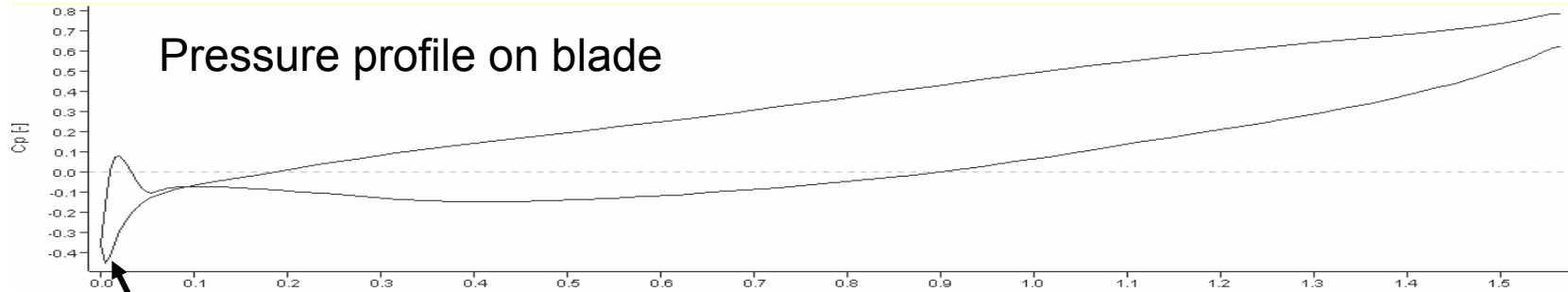
NPSH-Value [m]

- $P_{t,inlet}$  = total pressure inlet [Pa]
- $P_{vapor}$  = vaporizing pressure [Pa]
- $\rho_{ref}$  = density of fluid [kg/m<sup>3</sup>]
- $g$  = gravity [m/s<sup>2</sup>]

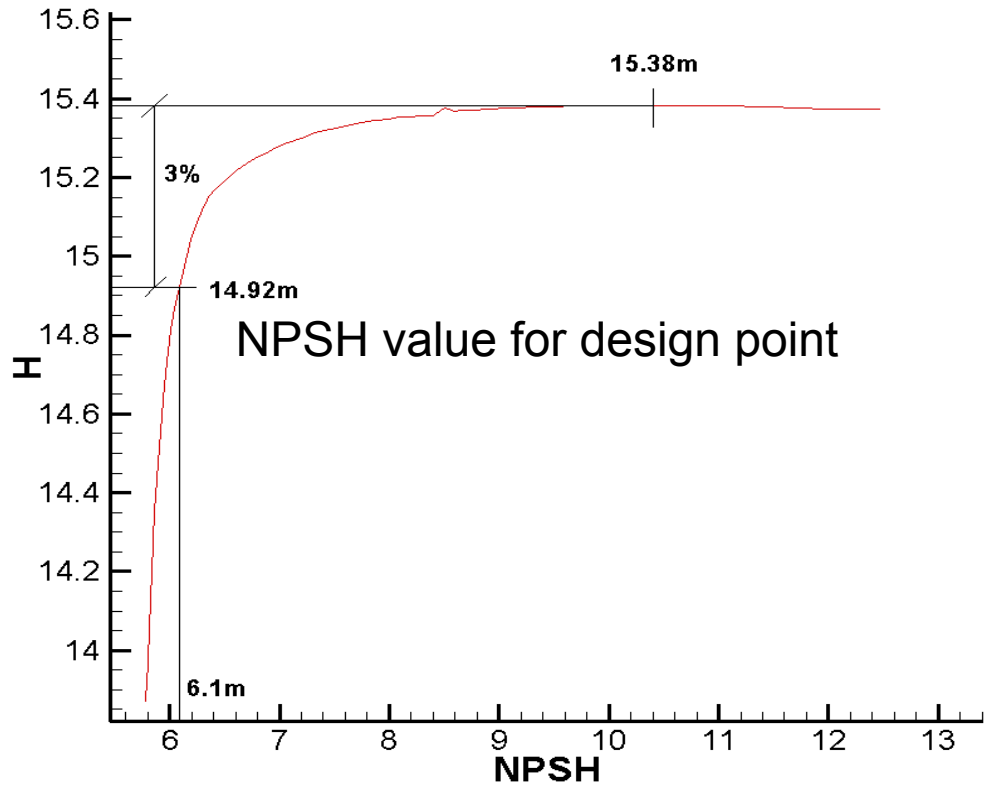




# NPSH Curve



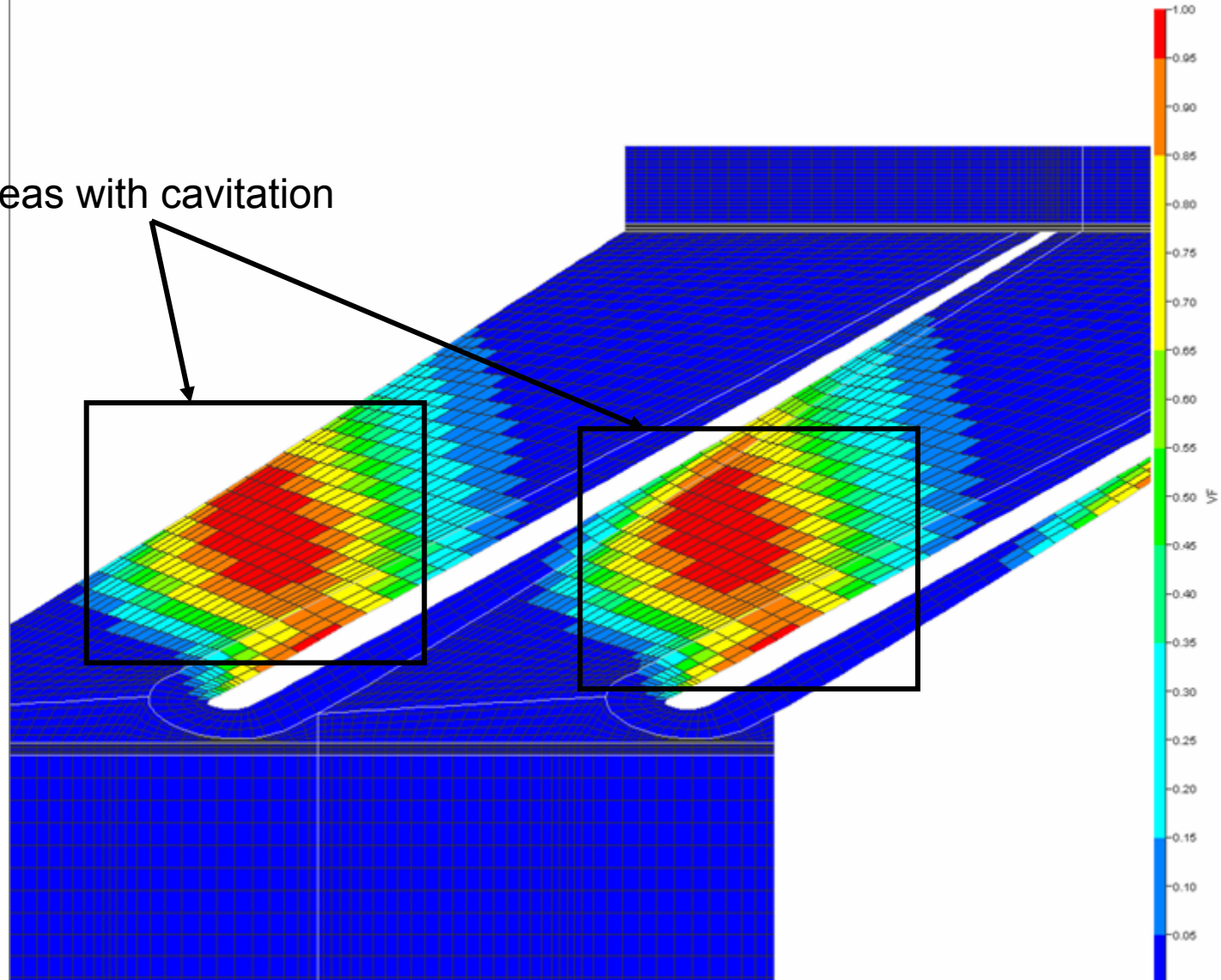
lowest pressure  
↓  
cavitate at first





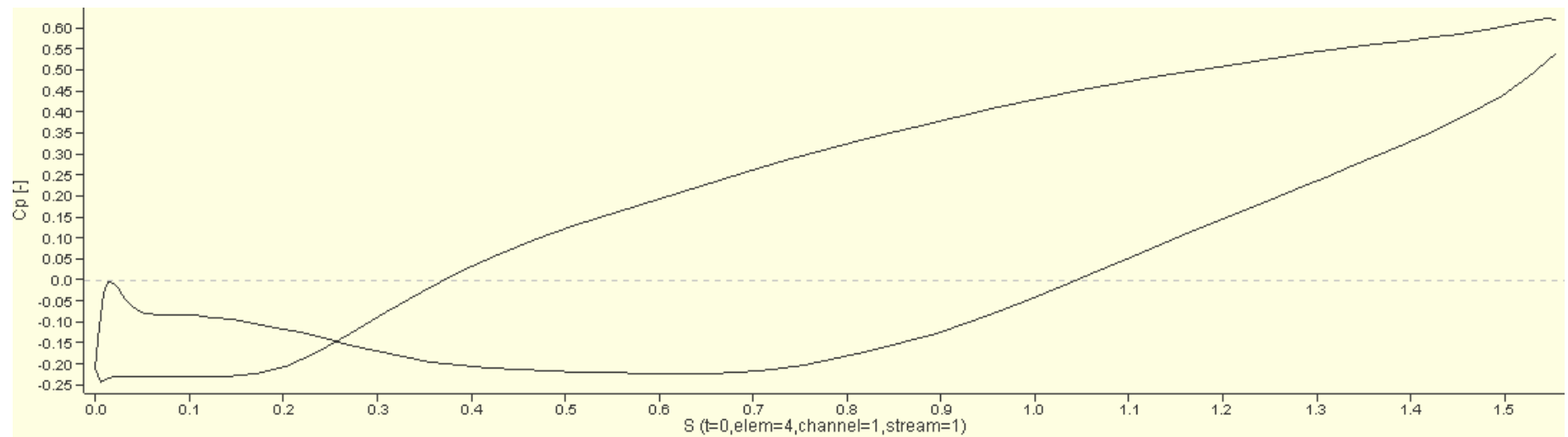
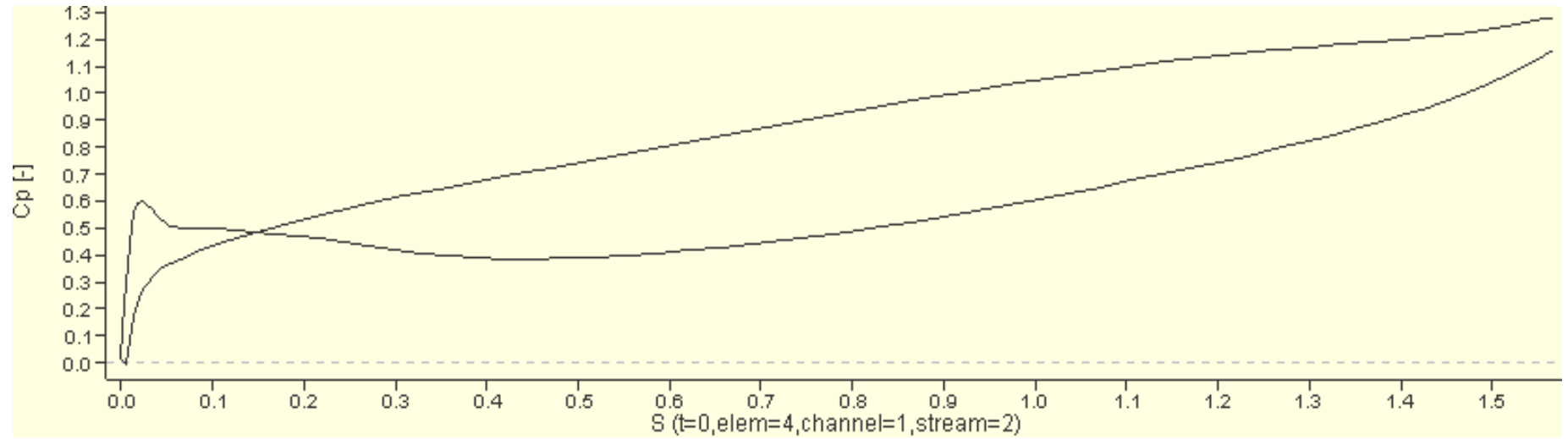
# Cavitation on blade

Areas with cavitation





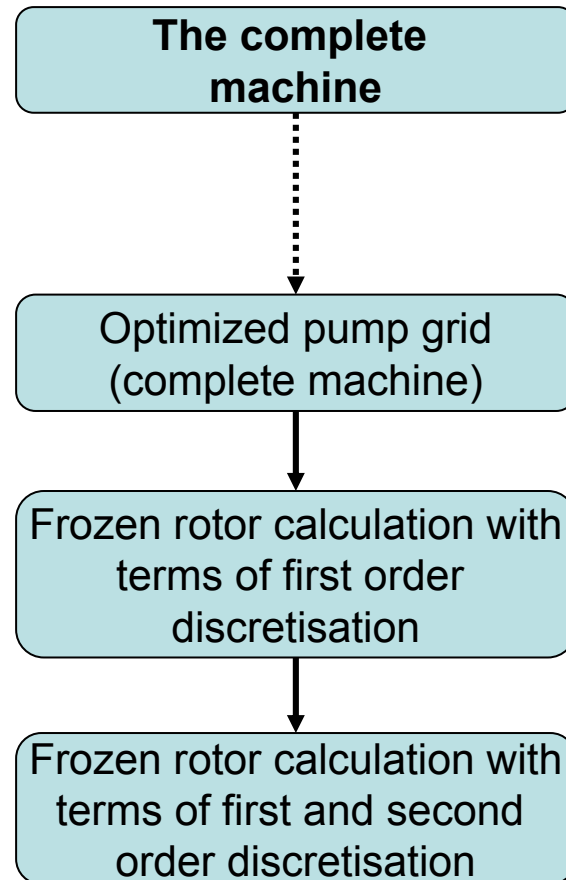
# Pressure profile on blade





# Complete machine

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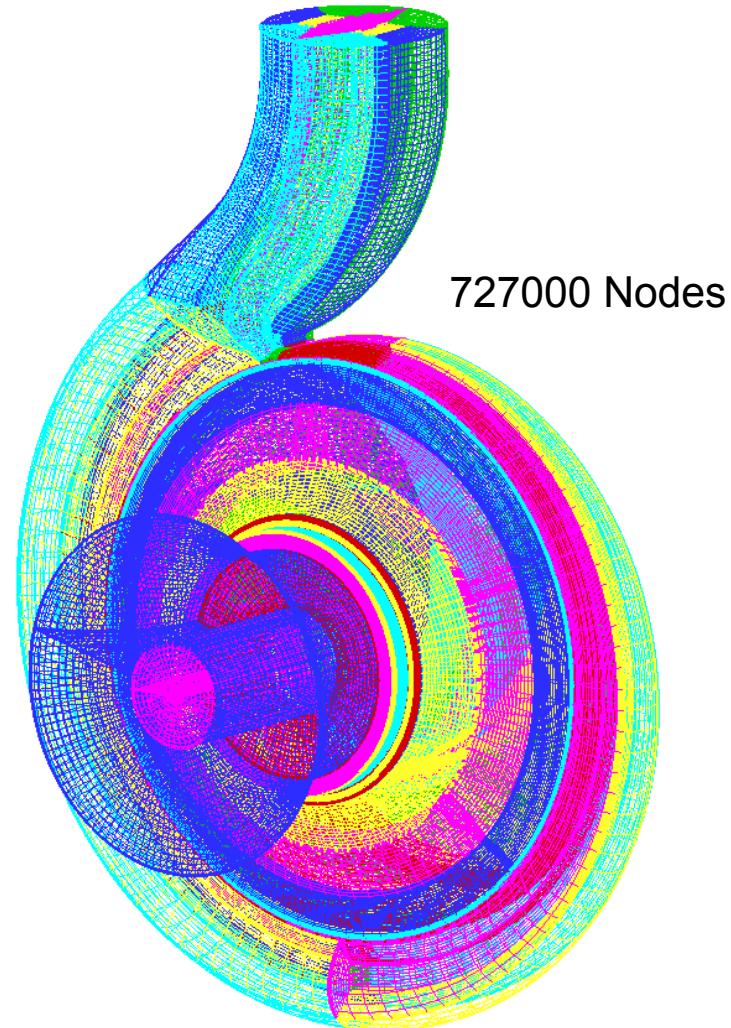




# The complete machine

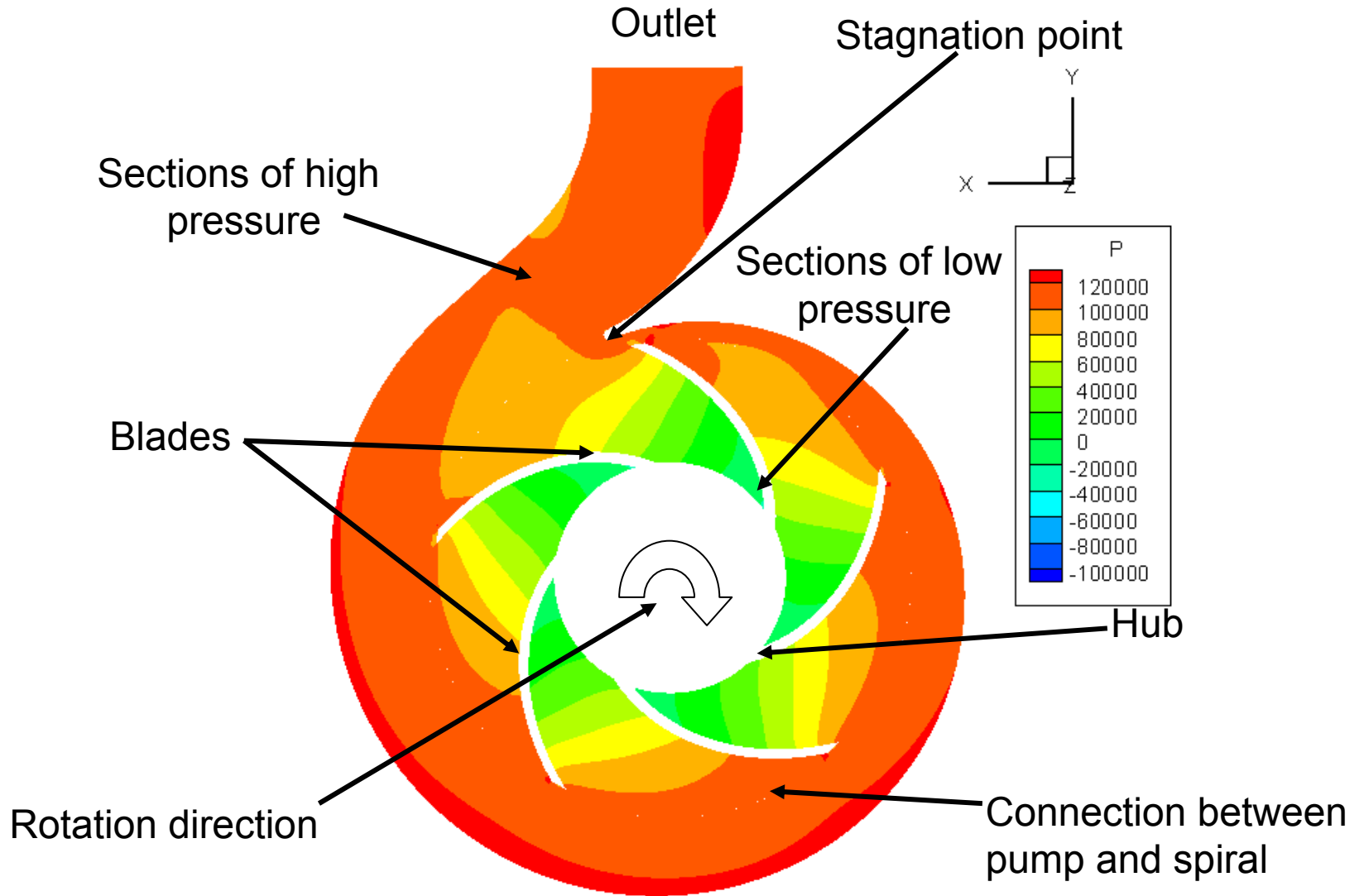
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- rotate grid with side space
- very resource intensive calculation
- connect spiral with rotated grid
- pump characteristic at design point
- frozen rotor calculation
- rotor change position in steps of 9 degree
- characteristic through different rotor settings



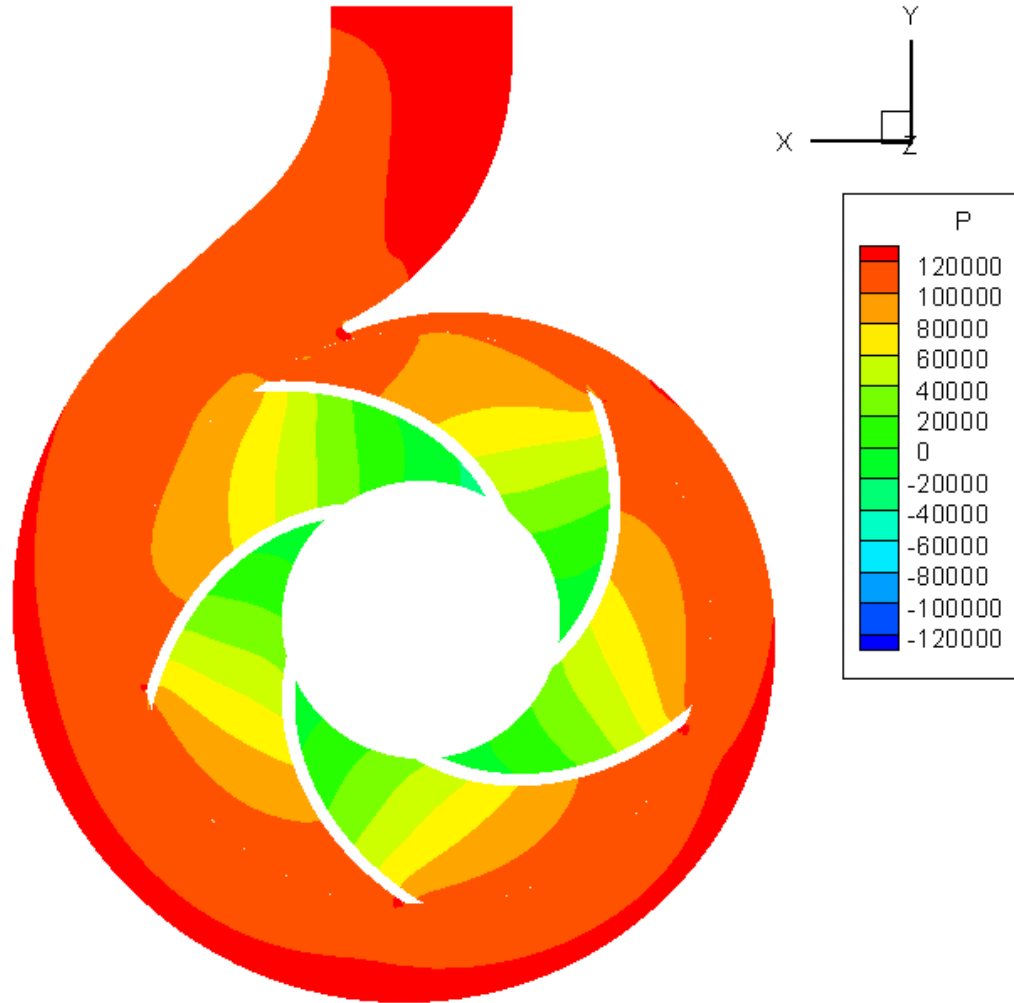


# Pressure profile 0°





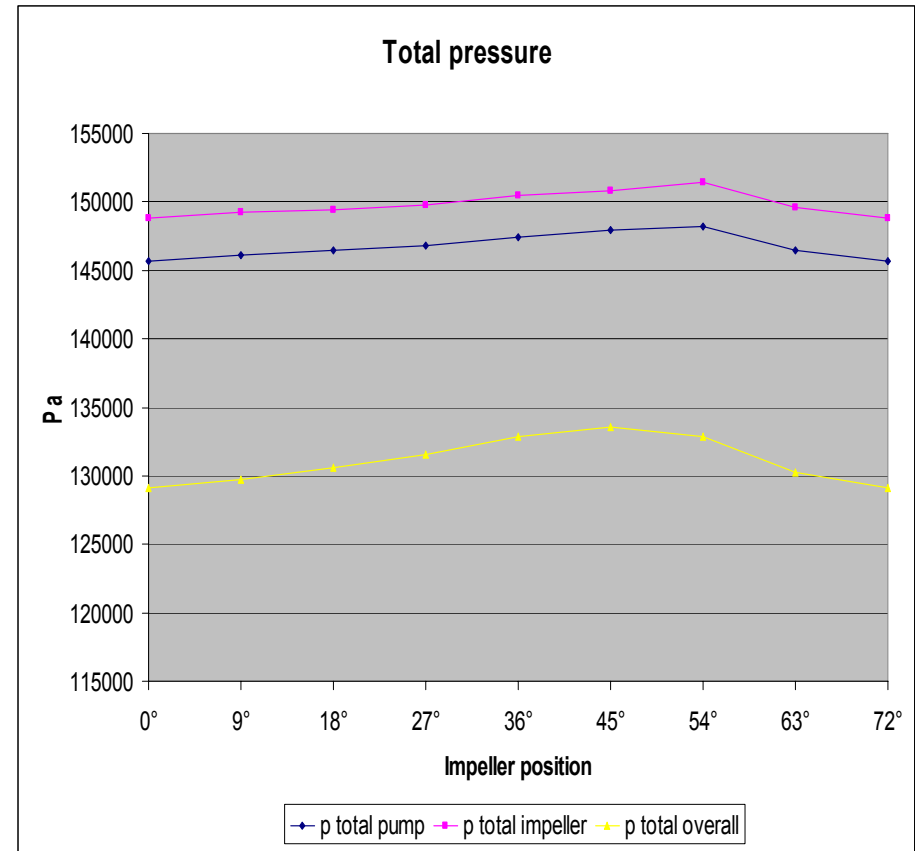
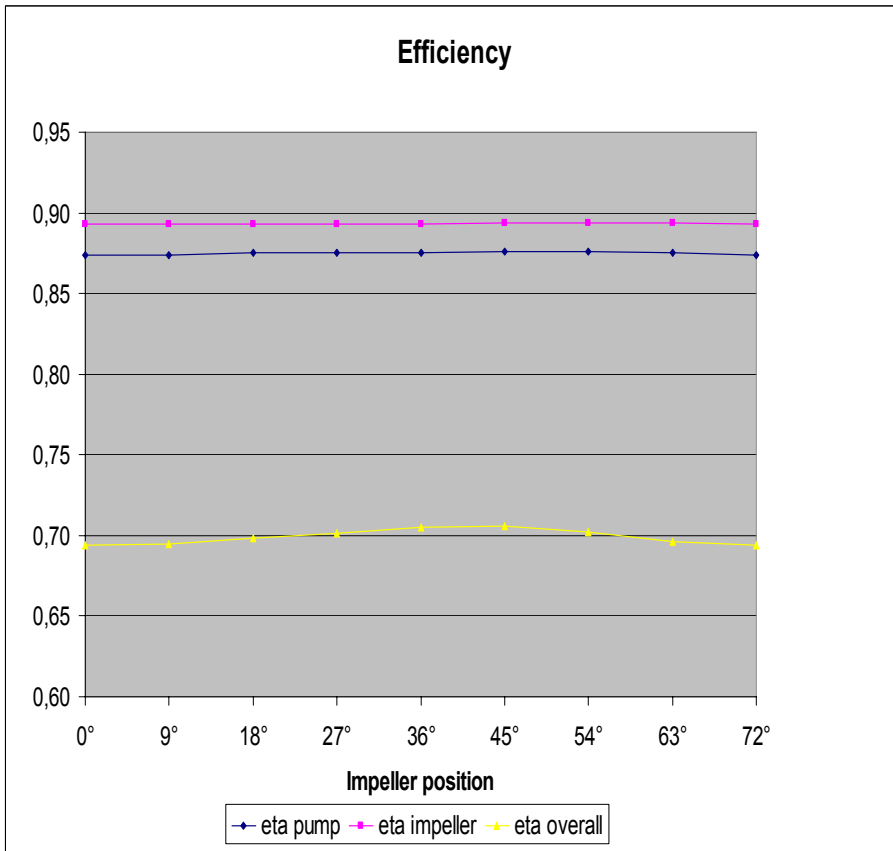
# Pressure profile 45°





# Comparison of results

Total pressure and efficiency depend on rotor position





# Conclusions

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- It is possible to mesh pump geometry with the given meshing tools.
- An iterative procedure is the best procedure to get the results.
- It is possible to get results only with the given inputs.
- The results of the IDS-Suite matching with the results of the industrial test rig.
- It is possible to design a centrifugal pump with CAE



## Discussion

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**Thank you**

**Discussion**