There are many practically important optimization problems that are NP-hard.

What can we do?

- Heuristics.
- Exploit special structure of instances occurring in practise.
- Consider algorithms that do not compute the optimal solution but provide solutions that are close to optimum.

Definition 2

An α -approximation for an optimization problem is a polynomial-time algorithm that for all instances of the problem produces a solution whose value is within a factor of α of the value of an optimal solution.

Minimization Problem:

Let $\mathcal I$ denote the set of problem instances, and let for a given instance $I \in \mathcal I$, $\mathcal F(I)$ denote the set of feasible solutions. Further let $\cos t(F)$ denote the cost of a feasible solution $F \in \mathcal F$.

Let for an algorithm A and instance $I \in \mathcal{I}$, $A(I) \in \mathcal{F}(I)$ denote the feasible solution computed by A. Then A is an approximation algorithm with approximation guarantee $\alpha \geq 1$ if

$$\forall I \in \mathcal{I} : cost(A(I)) \le \alpha \cdot \min_{F \in \mathcal{T}(I)} \{ cost(F) \} = \alpha \cdot OPT(I)$$

Maximization Problem:

Let $\mathcal I$ denote the set of problem instances, and let for a given instance $I \in \mathcal I$, $\mathcal F(I)$ denote the set of feasible solutions. Further let $\operatorname{profit}(F)$ denote the profit of a feasible solution $F \in \mathcal F$.

Let for an algorithm A and instance $I \in \mathcal{I}$, $A(I) \in \mathcal{F}(I)$ denote the feasible solution computed by A. Then A is an approximation algorithm with approximation guarantee $\alpha \leq 1$ if

$$\forall I \in \mathcal{I} : cost(A(I)) \ge \alpha \cdot \max_{F \in \mathcal{F}(I)} \{profit(F)\} = \alpha \cdot OPT(I)$$

Why approximation algorithms?

- We need algorithms for hard problems.
- It gives a rigorous mathematical base for studying heuristics.
- It provides a metric to compare the difficulty of various optimization problems.
- Proving theorems may give a deeper theoretical understanding which in turn leads to new algorithmic approaches.

Why not?

Sometimes the results are very pessimistic due to the fact that an algorithm has to provide a close-to-optimum solution on every instance.

What can we hope for?

Definition 3

A polynomial-time approximation scheme (PTAS) is a family of algorithms $\{A_{\epsilon}\}$, such that A_{ϵ} is a $(1+\epsilon)$ -approximation algorithm (for minimization problems) or a $(1-\epsilon)$ -approximation algorithm (for maximization problems).

Many NP-complete problems have polynomial time approximation schemes.

There are difficult problems!

The class MAX SNP (which we do not define) contains optimization problems like maximum cut or MAX-3SAT.

Theorem 4

For any MAX SNP-hard problem, there does not exist a polynomial-time approximation scheme, unless P = NP.

MAXCUT. Given a graph G = (V, E); partition V into two disjoint pieces A and B s.t. the number of edges between both pieces is maximized.

MAX-3SAT. Given a 3CNF-formula. Find an assignment to the variables that satisfies the maximum number of clauses.

There are really difficult problems!

Theorem 5

For any constant $\epsilon>0$ there does not exist an $\Omega(n^{\epsilon-1})$ -approximation algorithm for the maximum clique problem on a given graph G with n nodes unless P=NP.

Note that an 1/n-approximation is trivial.