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Definition 2

An α -approximation for an optimization problem is a polynomial-time algorithm that for all instances of the problem produces a solution whose value is within a factor of α of the value of an optimal solution.



Minimization Problem:

Let \mathcal{I} denote the set of problem instances, and let for a given instance $I \in \mathcal{I}$, $\mathcal{F}(I)$ denote the set of feasible solutions. Further let cost(F) denote the cost of a feasible solution $F \in \mathcal{F}$.

Let for an algorithm A and instance $I \in \mathcal{I}$, $A(I) \in \mathcal{F}(I)$ denote the feasible solution computed by A. Then A is an approximation algorithm with approximation guarantee $\alpha \ge 1$ if

$$\forall I \in \mathcal{I} : \operatorname{cost}(A(I)) \le \alpha \cdot \min_{F \in \mathcal{F}(I)} \{\operatorname{cost}(F)\} = \alpha \cdot \operatorname{OPT}(I)$$



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- It provides a metric to compare the difficulty of various optimization problems.
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What can we hope for?

Definition 3

A polynomial-time approximation scheme (PTAS) is a family of algorithms $\{A_{\epsilon}\}$, such that A_{ϵ} is a $(1 + \epsilon)$ -approximation algorithm (for minimization problems) or a $(1 - \epsilon)$ -approximation algorithm (for maximization problems).

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The class MAX SNP (which we do not define) contains optimization problems like maximum cut or MAX-3SAT.

Theorem 4

For any MAX SNP-hard problem, there does not exist a polynomial-time approximation scheme, unless P = NP.

MAXCUT. Given a graph G = (V, E); partition V into two disjoint pieces A and B s.t. the number of edges between both pieces is maximized.

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