4 Simplex Algorithm

Enumerating all basic feasible solutions (BFS), in order to find the optimum is slow.

Simplex Algorithm [George Dantzig 1947]

Move from BFS to adjacent BFS, without decreasing objective function.

Two BFSs are called adjacent if the bases just differ in one variable.

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Pivoting Step

basis =
$$\{s_c, s_h, s_m\}$$

 $a = b = 0$
 $Z = 0$
 $s_c = 480$
 $s_h = 160$
 $s_m = 1190$

- choose variable to bring into the basis
- chosen variable should have positive coefficient in objective function
- apply min-ratio test to find out by how much the variable can be increased
- pivot on row found by min-ratio test
- the existing basis variable in this row leaves the basis

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basis =
$$\{s_c, s_h, s_m\}$$

 $A = B = 0$
 $Z = 0$
 $s_c = 480$
 $s_h = 160$
 $s_m = 1190$

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basis = $\{s_c, s_h, s_m\}$ a = b = 0 Z = 0 $s_c = 480$ $s_h = 160$ $s_m = 1190$

- ▶ Choose variable with coefficient ≥ 0 as entering variable.
- ▶ If we keep a=0 and increase b from 0 to $\theta>0$ s.t. all constraints ($Ax=b,x\geq 0$) are still fulfilled the objective value Z will strictly increase.
- ► For maintaining Ax = b we need e.g. to set $s_c = 480 15\theta$.
- ► Choosing $\theta = \min\{480/15, 160/4, 1190/20\}$ ensures that in the new solution one current basic variable becomes 0, and no variable goes negative.
- ► The basic variable in the row that gives $min\{480/15, 160/4, 1190/20\}$ becomes the leaving variable.

basis =
$$\{s_c, s_h, s_m\}$$

 $a = b = 0$
 $Z = 0$
 $s_c = 480$
 $s_h = 160$
 $s_m = 1190$

Substitute $b = \frac{1}{15}(480 - 5a - s_c)$.

$$\begin{array}{lllll} \max Z & & & & \\ \frac{16}{3}a & -\frac{23}{15}s_c & & -Z = -736 \\ \frac{1}{3}a + b + \frac{1}{15}s_c & & = 32 \\ \frac{8}{3}a & -\frac{4}{15}s_c + s_h & & = 32 \\ \frac{85}{3}a & -\frac{4}{3}s_c & +s_m & = 550 \\ & a \ , \ b \ , \quad s_c \ , s_h \ , s_m & \geq 0 \end{array}$$

basis =
$$\{b, s_h, s_m\}$$

 $a = s_c = 0$
 $Z = 736$
 $b = 32$
 $s_h = 32$
 $s_m = 550$

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Pivoting stops when all coefficients in the objective function are non-positive.

Solution is optimal:

- any feasible solution satisfies all equations in the tableaux
- ▶ in particular: $Z = 800 s_c 2s_h, s_c \ge 0, s_h \ge 0$
- ▶ hence optimum solution value is at most 800
- ▶ the current solution has value 800

$$\begin{array}{llll} \max Z \\ \frac{16}{3}a + & \frac{23}{15}s_c & -Z = -736 \\ \frac{1}{3}a + b + \frac{1}{15}s_c & = 32 \\ \frac{8}{3}a + & -\frac{4}{15}s_c + s_h & = 32 \\ \frac{85}{3}a + & -\frac{4}{3}s_c & + s_m & = 550 \\ a , b , s_c , s_h , s_m & \geq 0 \end{array}$$

basis = $\{b, s_h, s_m\}$ $a = s_c = 0$ Z = 736b = 32 $s_h = 32$ $s_m = 550$

Choose variable a to bring into basis.

Computing $min\{3 \cdot 32, 3 \cdot 32/8, 3 \cdot 550/85\}$ means pivot on line 2. Substitute $a = \frac{3}{8}(32 + \frac{4}{15}s_c - s_h)$.

basis =
$$\{a, b, s_m\}$$

 $s_c = s_h = 0$
 $Z = 800$
 $b = 28$
 $a = 12$
 $s_m = 210$

Matrix View

Let our linear program be

$$c_B^t x_B + c_N^t x_N = Z$$

$$A_B x_B + A_N x_N = b$$

$$x_B , x_N \ge 0$$

The simplex tableaux for basis *B* is

$$(c_N^t - c_B^t A_B^{-1} A_N) x_N = Z - c_B^t A_B^{-1} b$$

$$Ix_B + A_B^{-1} A_N x_N = A_B^{-1} b$$

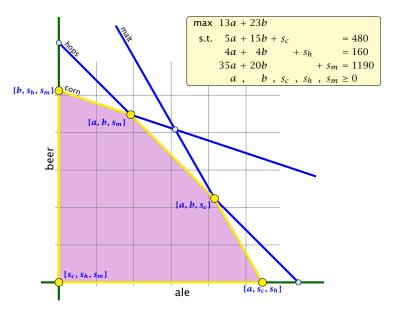
$$x_B , x_N \ge 0$$

The BFS is given by $x_N = 0$, $x_B = A_B^{-1}b$.

If $(c_N^t - c_R^t A_R^{-1} A_N) \le 0$ we know that we have an optimum solution.

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Geometric View of Pivoting



Algebraic Definition of Pivoting

Definition 2 (j-th basis direction)

Let B be a basis, and let $j \notin B$. The vector d with $d_j = 1$ and $d_\ell = 0, \ell \notin B, \ell \neq j$ and $d_B = -A_B^{-1}A_{*j}$ is called the j-th basis direction for B.

Going from x^* to $x^* + \theta \cdot d$ the objective function changes by

$$\theta \cdot c^t d = \theta (c_j - c_B^t A_B^{-1} A_{*j})$$

Algebraic Definition of Pivoting

- ▶ Given basis B with BFS x^* .
- ► Choose index $j \notin B$ in order to increase x_i^* from 0 to $\theta > 0$.
 - ▶ Other non-basis variables should stay at 0.
 - Basis variables change to maintain feasibility.
- Go from x^* to $x^* + \theta \cdot d$.

Requirements for *d*:

- $\rightarrow d_i = 1$ (normalization)
- $d_{\ell} = 0, \ \ell \notin B, \ \ell \neq j$
- $A(x^* + \theta d) = b$ must hold. Hence Ad = 0.
- ▶ Altogether: $A_B d_B + A_{*j} = Ad = 0$, which gives $d_B = -A_B^{-1} A_{*j}$.



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Algebraic Definition of Pivoting

Definition 3 (Reduced Cost)

For a basis *B* the value

$$\tilde{c}_i = c_i - c_B^t A_B^{-1} A_{*i}$$

is called the reduced cost for variable x_j .

Note that this is defined for every j. If $j \in B$ then the above term is 0.

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Algebraic Definition of Pivoting

Let our linear program be

$$c_B^t x_B + c_N^t x_N = Z$$

$$A_B x_B + A_N x_N = b$$

$$x_B , x_N \ge 0$$

The simplex tableaux for basis *B* is

The BFS is given by $x_N = 0$, $x_B = A_B^{-1}b$.

If $(c_N^t - c_B^t A_B^{-1} A_N) \le 0$ we know that we have an optimum solution.



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Min Ratio Test

The min ratio test computes a value $\theta \ge 0$ such that after setting the entering variable to θ the leaving variable becomes 0 and all other variables stay non-negative.

For this one computes b_i/A_{ie} for all constraints i and calculates the minimum positive value.

What does it mean that the ratio b_i/A_{ie} is negative for a constraint?

This means that the corresponding basic variable will increase if we increase b. Hence, there is no danger of this basic variable becoming negative

What happens if **all** b_i/A_{ie} are negative? Then we do not have a leaving variable. Then the LP is unbounded!

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Ouestions:

- What happens if the min ratio test fails to give us a value θ by which we can safely increase the entering variable?
- ▶ How do we find the initial basic feasible solution?
- ▶ Is there always a basis B such that

$$(c_N^t - c_R^t A_R^{-1} A_N) \le 0$$
 ?

Then we can terminate because we know that the solution is optimal.

▶ If yes how do we make sure that we reach such a basis?

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Termination

The objective function does not decrease during one iteration of the simplex-algorithm.

Does it always increase?

Termination

The objective function may not decrease!

Because a variable x_{ℓ} with $\ell \in B$ is already 0.

The set of inequalities is degenerate (also the basis is degenerate).

Definition 4 (Degeneracy)

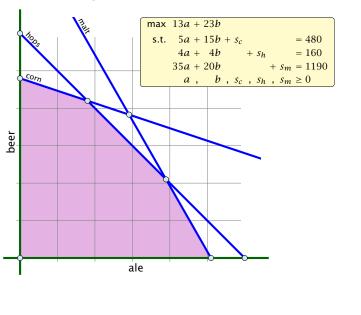
A BFS x^* is called degenerate if the set $J = \{j \mid x_j^* > 0\}$ fulfills |J| < m.

It is possible that the algorithm cycles, i.e., it cycles through a sequence of different bases without ever terminating. Happens, very rarely in practise.

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Non Degenerate Example



Summary: How to choose pivot-elements

- We can choose a column e as an entering variable if $\tilde{c}_e > 0$ (\tilde{c}_e is reduced cost for x_e).
- ▶ The standard choice is the column that maximizes \tilde{c}_e .
- ▶ If $A_{ie} \le 0$ for all $i \in \{1, ..., m\}$ then the maximum is not bounded.
- Otw. choose a leaving variable ℓ such that $b_{\ell}/A_{\ell e}$ is minimal among all variables i with $A_{ie} > 0$.
- If several variables have minimum $b_\ell/A_{\ell e}$ you reach a degenerate basis.
- ▶ Depending on the choice of ℓ it may happen that the algorithm runs into a cycle where it does not escape from a degenerate vertex.

Termination

What do we have so far?

Suppose we are given an initial feasible solution to an LP. If the LP is non-degenerate then Simplex will terminate.

Note that we either terminate because the min-ratio test fails and we can conclude that the LP is unbounded, or we terminate because the vector of reduced cost is non-positive. In the latter case we have an optimum solution.



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Two phase algorithm

Suppose we want to maximize $c^t x$ s.t. $Ax = b, x \ge 0$.

- 1. Multiply all rows with $b_i < 0$ by -1.
- 2. maximize $-\sum_i v_i$ s.t. Ax + I = b, $x \ge 0$, $v \ge 0$ using Simplex. x = 0, v = b is initial feasible.
- **3.** If $\sum_i v_i > 0$ then the original problem is infeasible.
- **4.** Otw. you have $x \ge 0$ with Ax = b.
- 5. From this you can get basic feasible solution.
- **6.** Now you can start the Simplex for the original problem.

How do we come up with an initial solution?

- $Ax \le b, x \ge 0$, and $b \ge 0$.
- ► The standard slack from for this problem is $Ax + Is = b, x \ge 0, s \ge 0$, where s denotes the vector of slack variables.
- ▶ Then s = b, x = 0 is a basic feasible solution (how?).
- ▶ We directly can start the simplex algorithm.

How do we find an initial basic feasible solution for an arbitrary problem?



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Optimality

Lemma 5

Let B be a basis and x^* a BFS corresponding to basis B. $\tilde{c} \le 0$ implies that x^* is an optimum solution to the LP.