Given n items with sizes s_1, \ldots, s_n where

```
1 > s_1 \ge \cdots \ge s_n > 0.
```

Pack items into a minimum number of bins where each bin can hold items of total size at most 1.

Theorem 5 There is no ρ -approximation for Bin Packing with $\rho < 3/2$ unless P = NP.



17.3 Bin Packing

Given n items with sizes s_1, \ldots, s_n where

```
1 > s_1 \ge \cdots \ge s_n > 0.
```

Pack items into a minimum number of bins where each bin can hold items of total size at most 1.

Theorem 5

There is no ρ -approximation for Bin Packing with $\rho < 3/2$ unless P = NP.



Proof

▶ In the partition problem we are given positive integers $b_1, ..., b_n$ with $B = \sum_i b_i$ even. Can we partition the integers into two sets *S* and *T* s.t.

$$\sum_{i\in S} b_i = \sum_{i\in T} b_i \quad ?$$

- We can solve this problem by setting $s_i := 2b_i/B$ and asking whether we can pack the resulting items into 2 bins or not.
- A ρ-approximation algorithm with ρ < 3/2 cannot output 3 or more bins when 2 are optimal.
- Hence, such an algorithm can solve Partition.



Proof

▶ In the partition problem we are given positive integers $b_1, ..., b_n$ with $B = \sum_i b_i$ even. Can we partition the integers into two sets *S* and *T* s.t.

$$\sum_{i\in S} b_i = \sum_{i\in T} b_i \quad ?$$

- We can solve this problem by setting $s_i := 2b_i/B$ and asking whether we can pack the resulting items into 2 bins or not.
- A ρ-approximation algorithm with ρ < 3/2 cannot output 3 or more bins when 2 are optimal.
- Hence, such an algorithm can solve Partition.



17.3 Bin Packing

Proof

▶ In the partition problem we are given positive integers $b_1, ..., b_n$ with $B = \sum_i b_i$ even. Can we partition the integers into two sets *S* and *T* s.t.

$$\sum_{i\in S} b_i = \sum_{i\in T} b_i \quad ?$$

- We can solve this problem by setting $s_i := 2b_i/B$ and asking whether we can pack the resulting items into 2 bins or not.
- A ρ -approximation algorithm with $\rho < 3/2$ cannot output 3 or more bins when 2 are optimal.
- Hence, such an algorithm can solve Partition.



Proof

▶ In the partition problem we are given positive integers b_1, \ldots, b_n with $B = \sum_i b_i$ even. Can we partition the integers into two sets *S* and *T* s.t.

$$\sum_{i\in S} b_i = \sum_{i\in T} b_i \quad ?$$

- We can solve this problem by setting $s_i := 2b_i/B$ and asking whether we can pack the resulting items into 2 bins or not.
- A ρ -approximation algorithm with $\rho < 3/2$ cannot output 3 or more bins when 2 are optimal.
- Hence, such an algorithm can solve Partition.



Definition 6

An asymptotic polynomial-time approximation scheme (APTAS) is a family of algorithms $\{A_{\epsilon}\}$ along with a constant c such that A_{ϵ} returns a solution of value at most $(1 + \epsilon)$ OPT + c for minimization problems.

- Note that for Set Cover or for Knapsack it makes no sense to differentiate between the notion of a PTAS or an APTAS because of scaling.
- However, we will develop an APTAS for 8in Packing.



17.3 Bin Packing

Definition 6

An asymptotic polynomial-time approximation scheme (APTAS) is a family of algorithms $\{A_{\epsilon}\}$ along with a constant c such that A_{ϵ} returns a solution of value at most $(1 + \epsilon)$ OPT + c for minimization problems.

- Note that for Set Cover or for Knapsack it makes no sense to differentiate between the notion of a PTAS or an APTAS because of scaling.
- However, we will develop an APTAS for Bin Packing.



Definition 6

An asymptotic polynomial-time approximation scheme (APTAS) is a family of algorithms $\{A_{\epsilon}\}$ along with a constant c such that A_{ϵ} returns a solution of value at most $(1 + \epsilon)$ OPT + c for minimization problems.

- Note that for Set Cover or for Knapsack it makes no sense to differentiate between the notion of a PTAS or an APTAS because of scaling.
- However, we will develop an APTAS for Bin Packing.



Again we can differentiate between small and large items.

Lemma 7

Any packing of items of size at most γ into ℓ bins can be extended to a packing of all items into $\max\{\ell, \frac{1}{1-\gamma}SIZE(I) + 1\}$ bins, where $SIZE(I) = \sum_{i} s_i$ is the sum of all item sizes.

- If after Greedy we use more than ℓ bins, all bins (apart from the last) must be full to at least $1 - \gamma$. Hence, $r(1 - \gamma) \leq SIZE(I)$ where r is the number of
- nearly-full bins.
- This gives the lemma.



17.3 Bin Packing

Again we can differentiate between small and large items.

Lemma 7

Any packing of items of size at most γ into ℓ bins can be extended to a packing of all items into $\max\{\ell, \frac{1}{1-\gamma}SIZE(I) + 1\}$ bins, where $SIZE(I) = \sum_{i} s_i$ is the sum of all item sizes.

- ► If after Greedy we use more than ℓ bins, all bins (apart from the last) must be full to at least 1γ .
- Hence, r(1 − γ) ≤ SIZE(I) where r is the number of nearly-full bins.
- This gives the lemma.



17.3 Bin Packing

Again we can differentiate between small and large items.

Lemma 7

Any packing of items of size at most γ into ℓ bins can be extended to a packing of all items into $\max\{\ell, \frac{1}{1-\gamma}SIZE(I) + 1\}$ bins, where $SIZE(I) = \sum_{i} s_i$ is the sum of all item sizes.

- ► If after Greedy we use more than ℓ bins, all bins (apart from the last) must be full to at least 1γ .
- Hence, r(1 − y) ≤ SIZE(I) where r is the number of nearly-full bins.
- This gives the lemma.



Again we can differentiate between small and large items.

Lemma 7

Any packing of items of size at most γ into ℓ bins can be extended to a packing of all items into $\max\{\ell, \frac{1}{1-\gamma}SIZE(I) + 1\}$ bins, where $SIZE(I) = \sum_{i} s_i$ is the sum of all item sizes.

- ► If after Greedy we use more than ℓ bins, all bins (apart from the last) must be full to at least 1γ .
- Hence, r(1 − y) ≤ SIZE(I) where r is the number of nearly-full bins.
- This gives the lemma.



Choose $\gamma = \epsilon/2$. Then we either use ℓ bins or at most

$$\frac{1}{1 - \epsilon/2} \cdot \text{OPT} + 1 \le (1 + \epsilon) \cdot \text{OPT} + 1$$

bins.

It remains to find an algorithm for the large items.



Linear Grouping:

Generate an instance I' (for large items) as follows.

- Order large items according to size.
- Let the first k items belong to group 1; the following k items belong to group 2; etc.
- Delete items in the first group;
- Round items in the remaining groups to the size of the largest item in the group.



Linear Grouping:

Generate an instance I' (for large items) as follows.

- Order large items according to size.
- Let the first k items belong to group 1; the following k items belong to group 2; etc.
- Delete items in the first group;
- Round items in the remaining groups to the size of the largest item in the group.



17.3 Bin Packing

Linear Grouping:

Generate an instance I' (for large items) as follows.

- Order large items according to size.
- Let the first k items belong to group 1; the following k items belong to group 2; etc.
- Delete items in the first group;
- Round items in the remaining groups to the size of the largest item in the group.



Linear Grouping:

Generate an instance I' (for large items) as follows.

- Order large items according to size.
- Let the first k items belong to group 1; the following k items belong to group 2; etc.
- Delete items in the first group;
- Round items in the remaining groups to the size of the largest item in the group.



- \sim Any bin packing for I gives a bin packing for I' as follows.
- Pack the items of group 2, where in the packing for 4 the items for group 1 have been packed;
- Pack the Items of groups 3, where in the packing for 7 the items for group 2 have been packed;



- Any bin packing for I gives a bin packing for I' as follows.
- Pack the items of group 2, where in the packing for I the items for group 1 have been packed;
- Pack the items of groups 3, where in the packing for I the items for group 2 have been packed;



- Any bin packing for I gives a bin packing for I' as follows.
- Pack the items of group 2, where in the packing for I the items for group 1 have been packed;
- Pack the items of groups 3, where in the packing for I the items for group 2 have been packed;



- Any bin packing for I gives a bin packing for I' as follows.
- Pack the items of group 2, where in the packing for I the items for group 1 have been packed;
- Pack the items of groups 3, where in the packing for I the items for group 2 have been packed;



Proof 1:

- Any bin packing for I gives a bin packing for I' as follows.
- Pack the items of group 2, where in the packing for I the items for group 1 have been packed;
- Pack the items of groups 3, where in the packing for *I* the items for group 2 have been packed;



▶ ...

Lemma 9 OPT $(I') \le \text{OPT}(I) \le \text{OPT}(I') + k$

Proof 2:

- Any bin packing for I' gives a bin packing for I as follows.
- Pack the items of group 1 into k new bins;
- Pack the items of groups 2, where in the packing for I' the items for group 2 have been packed;

► ...



Proof 2:

- Any bin packing for I' gives a bin packing for I as follows.
- Pack the items of group 1 into k new bins;
- Pack the items of groups 2, where in the packing for I' the items for group 2 have been packed;



Lemma 9 OPT $(I') \le \text{OPT}(I) \le \text{OPT}(I') + k$

Proof 2:

- Any bin packing for I' gives a bin packing for I as follows.
- Pack the items of group 1 into k new bins;
- Pack the items of groups 2, where in the packing for I' the items for group 2 have been packed;



Lemma 9 OPT $(I') \le \text{OPT}(I) \le \text{OPT}(I') + k$

Proof 2:

- Any bin packing for I' gives a bin packing for I as follows.
- Pack the items of group 1 into k new bins;
- Pack the items of groups 2, where in the packing for I' the items for group 2 have been packed;

▶ ...



We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le 2n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (here we used $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$

We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le 2n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (here we used $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$

We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le 2n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (here we used $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$

We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le 2n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (here we used $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$

We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le 2n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (here we used $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$

We set $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$.

Then $n/k \le 2n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$ (here we used $\lfloor \alpha \rfloor \ge \alpha/2$ for $\alpha \ge 1$).

Hence, after grouping we have a constant number of piece sizes $(4/\epsilon^2)$ and at most a constant number $(2/\epsilon)$ can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$