There are many practically important optimization problems that are NP-hard.

What can we do?

- Heuristics.
- Exploit special structure of instances occurring in practise.
- Consider algorithms that do not compute the optimal solution but provide solutions that are close to optimum.

Definition 2

An α -approximation for an optimization problem is a polynomial-time algorithm that for all instances of the problem produces a solution whose value is within a factor of α of the value of an optimal solution.

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255

Why approximation algorithms?

- > We need algorithms for hard problems.
- It gives a rigorous mathematical base for studying heuristics.
- It provides a metric to compare the difficulty of various optimization problems.
- Proving theorems may give a deeper theoretical understanding which in turn leads to new algorithmic approaches.

Why not?

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 Sometimes the results are very pessimistic due to the fact that an algorithm has to provide a close-to-optimum solution on every instance.

256

254

Definition 3

An optimization problem P = (1, sol, m, goal) is in **NPO** if

- $x \in \mathcal{I}$ can be decided in polynomial time
- $y \in sol(\mathcal{I})$ can be verified in polynomial time
- *m* can be computed in polynomial time
- goal $\in \{\min, \max\}$

In other words: the decision problem is there a solution y with m(x, y) at most/at least z is in NP.

- ► *x* is problem instance
- y is candidate solution
- $m^*(x)$ cost/profit of an optimal solution

Definition 4 (Performance Ratio)

$$R(x, y) := \max\left\{\frac{m(x, y)}{m^*(x)}, \frac{m^*(x)}{m(x, y)}\right\}$$

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Definition 6 (PTAS)

A PTAS for a problem *P* from NPO is an algorithm that takes as input $x \in I$ and $\epsilon > 0$ and produces a solution γ for x with

$R(x, y) \leq 1 + \epsilon$.

The running time is polynomial in |x|.

approximation with arbitrary good factor... fast?

Definition 5 (r -approximation) An algorithm A is an r -approximation algorithm iff	
$\forall x \in \mathcal{I} : R(x, A(x)) \leq r$,	
and A runs in polynomial time.	

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Problems that have a PTAS

Scheduling. Given m jobs with known processing times; schedule the jobs on n machines such that the MAKESPAN is minimized.

258

259

Definition 7 (FPTAS)

An FPTAS for a problem *P* from NPO is an algorithm that takes as input $x \in \mathcal{I}$ and $\epsilon > 0$ and produces a solution \mathcal{Y} for x with

$R(x,y) \leq 1 + \epsilon$.

The running time is polynomial in |x| and $1/\epsilon$.

approximation with arbitrary good factor... fast!

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Definition 8 (APX – approximable)

A problem *P* from NPO is in APX if there exist a constant $r \ge 1$ and an *r*-approximation algorithm for *P*.

constant factor approximation...

Problems	that	have	an	FP	TAS
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KNAPSACK. Given a set of items with profits and weights choose a subset of total weight at most W s.t. the profit is maximized.

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263

Problems that are in APX

MAXCUT. Given a graph G = (V, E); partition V into two disjoint pieces A and B s.t. the number of edges between both pieces is maximized.

MAX-3SAT. Given a 3CNF-formula. Find an assignment to the variables that satisfies the maximum number of clauses.

262

Problems with polylogarithmic approximation guarantees

- Set Cover
- Minimum Multicut
- Sparsest Cut
- Minimum Bisection

There is an r-approximation with $r \leq O(\log^{c}(|x|))$ for some constant c.

Note that only for some of the above problem a matching lower bound is known.

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266

There are weird problems!

Asymmetric *k*-Center admits an $O(\log^* n)$ -approximation.

There is no $o(\log^* n)$ -approximation to Asymmetric *k*-Center unless $NP \subseteq DTIME(n^{\log \log \log n})$.

There are	e really	difficult	problems!
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Theorem 9

For any constant $\epsilon > 0$ there does not exist an $\Omega(n^{1-\epsilon})$ -approximation algorithm for the maximum clique problem on a given graph *G* with *n* nodes unless P = NP.

Note that an *n*-approximation is trivial.

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Class APX not important in practise. Instead of saying problem *P* is in APX one says problem *P* admits a 4-approximation. One only says that a problem is APX-hard.

267