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Can we obtain a better analysis?



Observation

Simplex visits every feasible basis at most once.



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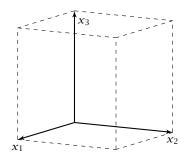
Simplex visits every feasible basis at most once.

However, also the number of feasible bases can be very large.



Example

$$\begin{array}{c}
\text{max } c^T x \\
\text{s.t. } 0 \le x_1 \le 1 \\
0 \le x_2 \le 1 \\
\vdots \\
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\end{array}$$



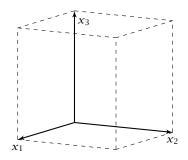
2n constraint on n variables define an n-dimensional hypercube as feasible region.

The feasible region has 2^n vertices.



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However, Simplex may still run quickly as it usually does not visit all feasible bases.

In the following we give an example of a feasible region for which there is a bad Pivoting Rule.

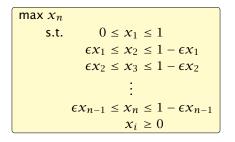


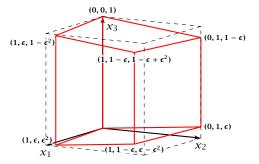
Pivoting Rule

A Pivoting Rule defines how to choose the entering and leaving variable for an iteration of Simplex.

In the non-degenerate case after choosing the entering variable the leaving variable is unique.







- ▶ We have 2*n* constraints, and 3*n* variables (after adding slack variables to every constraint).
- Every basis is defined by 2n variables, and n non-basic variables.
- There exist degenerate vertices.
- The degeneracies come from the non-negativity constraints, which are superfluous.
- In the following all variables x_i stay in the basis at all times
- ▶ Then, we can uniquely specify a basis by choosing for each variable whether it should be equal to its lower bound, or equal to its upper bound (the slack variable corresponding to the non-tight constraint is part of the basis).
- ▶ We can also simply identify each basis/vertex with the corresponding hypercube vertex obtained by letting $\epsilon \to 0$.

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- In the following we specify a sequence of bases (identified by the corresponding hypercube node) along which the objective function strictly increases.
- ► The basis (0,...,0,1) is the unique optimal basis.
- Our sequence S_n starts at (0,...,0) ends with (0,...,0,1) and visits every node of the hypercube.
- An unfortunate Pivoting Rule may choose this sequence, and, hence, require an exponential number of iterations.



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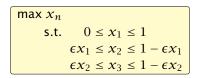


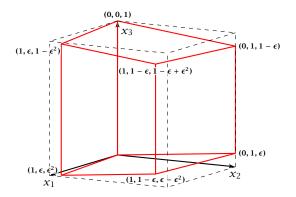
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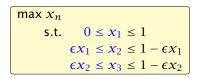


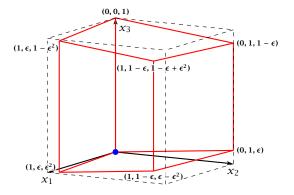
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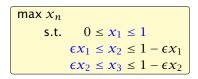


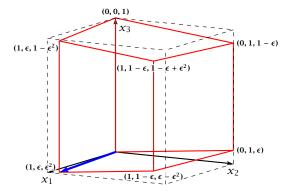


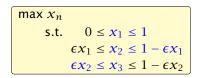


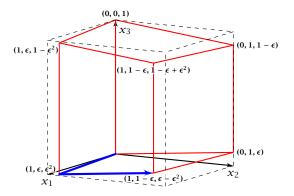


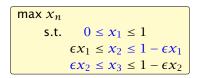


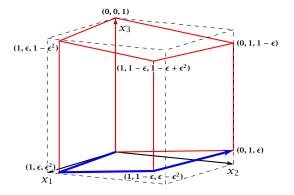


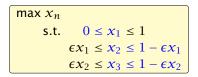


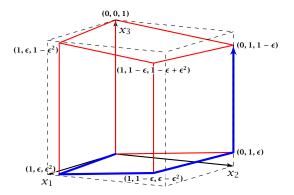


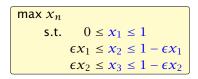


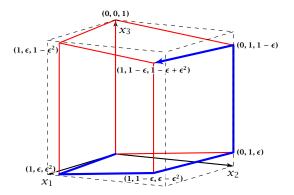


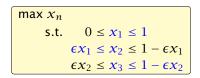


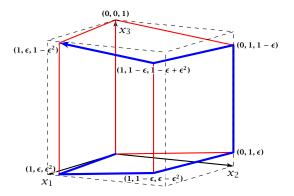


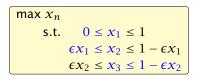


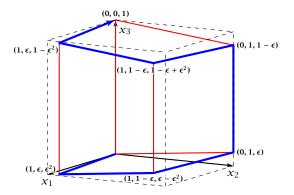




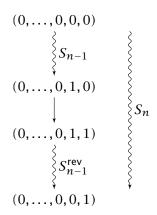








The sequence S_n that visits every node of the hypercube is defined recursively



The non-recursive case is $S_1 = 0 \rightarrow 1$



Lemma 2

The objective value x_n is increasing along path S_n .

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Proof by induction:
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n = 1: obvious, since S_1 = 0 \rightarrow 1, and 1 > 0.
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- ▶ Going from (0,...,0,1,0) to (0,...,0,1,1) increases x_n for small enough ϵ .
- ▶ For the remaining path S_{n-1}^{rev} we have $x_n = 1 \epsilon x_{n-1}$.
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Observation

The simplex algorithm takes at most $\binom{n}{m}$ iterations. Each iteration can be implemented in time $\mathcal{O}(mn)$.

In practise it usually takes a linear number of iterations.



Theorem

For almost all known deterministic pivoting rules (rules for choosing entering and leaving variables) there exist lower bounds that require the algorithm to have exponential running time ($\Omega(2^{\Omega(n)})$) (e.g. Klee Minty 1972).



Theorem

For some standard randomized pivoting rules there exist subexponential lower bounds ($\Omega(2^{\Omega(n^{\alpha})})$ for $\alpha>0$) (Friedmann, Hansen, Zwick 2011).



Conjecture (Hirsch 1957)

The edge-vertex graph of an m-facet polytope in d-dimensional Euclidean space has diameter no more than m-d.

The conjecture has been proven wrong in 2010.

But the question whether the diameter is perhaps of the form $\mathcal{O}(\operatorname{poly}(m,d))$ is open.

