Given *n* items with sizes  $s_1, \ldots, s_n$  where

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Pack items into a minimum number of bins where each bin can hold items of total size at most 1.

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17.3 Bin Packing

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#### Proof

▶ In the partition problem we are given positive integers  $b_1, \ldots, b_n$  with  $B = \sum_i b_i$  even. Can we partition the integers into two sets *S* and *T* s.t.

$$\sum_{i\in S} b_i = \sum_{i\in T} b_i \quad ?$$

- We can solve this problem by setting  $s_i := 2b_i/B$  and asking whether we can pack the resulting items into 2 bins or not.
- A ρ-approximation algorithm with ρ < 3/2 cannot output 3 or more bins when 2 are optimal.
- Hence, such an algorithm can solve Partition.

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#### **Definition 6**

An asymptotic polynomial-time approximation scheme (APTAS) is a family of algorithms  $\{A_{\epsilon}\}$  along with a constant c such that  $A_{\epsilon}$  returns a solution of value at most  $(1 + \epsilon)$ OPT + c for minimization problems.

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Again we can differentiate between small and large items.

Lemma 7

Any packing of items into  $\ell$  bins can be extended with items of size at most  $\gamma$  s.t. we use only  $\max\{\ell, \frac{1}{1-\gamma}SIZE(I) + 1\}$  bins, where  $SIZE(I) = \sum_i s_i$  is the sum of all item sizes.

- If after Greedy we use more than 6 bins, all bins (apart from the last) must be full to at least 1 = 1;
- Hence, 2014-2012/00/Where 2015 the number of a nearly-full bins.
- This gives the lemma.



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Choose  $\gamma = \epsilon/2$ . Then we either use  $\ell$  bins or at most

$$\frac{1}{1 - \epsilon/2} \cdot \text{OPT} + 1 \le (1 + \epsilon) \cdot \text{OPT} + 1$$

bins.

It remains to find an algorithm for the large items.



#### Linear Grouping:

Generate an instance I' (for large items) as follows.

- Order large items according to size.
- Let the first k items belong to group 1; the following k items belong to group 2; etc.
- Delete items in the first group;
- Round items in the remaining groups to the size of the largest item in the group.



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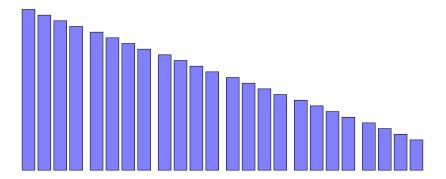
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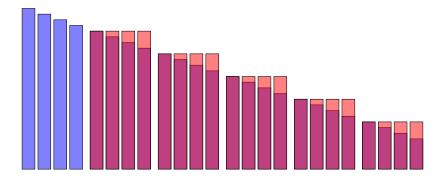






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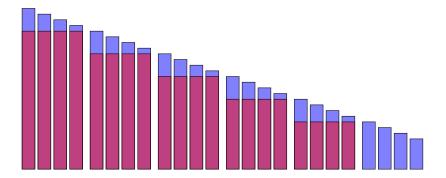
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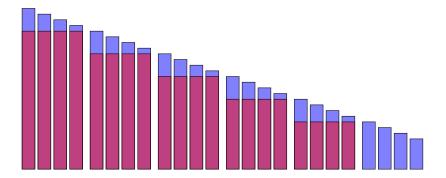
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- Any bin packing for / gives a bin packing for / as follows.
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- Any bin packing for I' gives a bin packing for I as follows.
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We set  $k = \lfloor \epsilon \text{SIZE}(I) \rfloor$ .

Then  $n/k \le n/\lfloor \epsilon^2 n/2 \rfloor \le 4/\epsilon^2$  (here we used  $\lfloor \alpha \rfloor \ge \alpha/2$  for  $\alpha \ge 1$ ).

Hence, after grouping we have a constant number of piece sizes  $(4/\epsilon^2)$  and at most a constant number  $(2/\epsilon)$  can fit into any bin.

We can find an optimal packing for such instances by the previous Dynamic Programming approach.

cost (for large items) at most

 $OPT(I') + k \le OPT(I) + \epsilon SIZE(I) \le (1 + \epsilon)OPT(I)$ 

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