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Together with the obervation that if each $p_i \ge \frac{1}{3}C_{\max}^*$ then LPT is optimal this gave a 4/3-approximation.



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1. Find the optimum Makespan for the long jobs by brute force.



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Idea:

- 1. Find the optimum Makespan for the long jobs by brute force.
- 2. Then use the list scheduling algorithm for the short jobs, always assigning the next job to the least loaded machine.



We still have the inequality

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If ℓ is a short job its length is at most

$$p_\ell \leq \sum_j p_j/(mk)$$

which is at most C_{max}^*/k .



Hence we get a schedule of length at most

$$\left(1+\frac{1}{k}\right)C_{\max}^*$$

There are at most km long jobs. Hence, the number of possibilities of scheduling these jobs on m machines is at most m^{km} , which is constant if m is constant. Hence, it is easy to implement the algorithm in polynomial time.

Theorem 3

The above algorithm gives a polynomial time approximation scheme (PTAS) for the problem of scheduling n jobs on m identical machines if m is constant.

We choose $k = \lceil \frac{1}{\epsilon} \rceil$.





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We first design an algorithm that works as follows: On input of T it either finds a schedule of length $(1+\frac{1}{k})T$ or certifies that no schedule of length at most T exists (assume $T \ge \frac{1}{m} \sum_{i} p_{i}$).

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- ▶ We round all long jobs down to multiples of T/k^2 .
- For these rounded sizes we first find an optimal schedule.
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After the first phase the rounded sizes of the long jobs assigned to a machine add up to at most T.

There can be at most k (long) jobs assigned to a machine as otw. their rounded sizes would add up to more than T (note that the rounded size of a long job is at least T/k).

Since, jobs had been rounded to multiples of T/k^2 going from rounded sizes to original sizes gives that the Makespan is at most

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Hence, any large job has rounded size of $\frac{i}{k^2}T$ for $i\in\{k,\ldots,k^2\}$. Therefore the number of different inputs is at most n^{k^2} (described by a vector of length k^2 where, the i-th entry describes the number of jobs of size $\frac{i}{k^2}T$). This is polynomial.

The schedule/configuration of a particular machine x can be described by a vector of length k^2 where the i-th entry describes the number of jobs of rounded size $\frac{i}{k^2}T$ assigned to x. There are only $(k+1)^{k^2}$ different vectors.



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If $OPT(n_1, \ldots, n_{k^2}) \leq m$ we can schedule the input.

We have

 $OPT(n_1,\ldots,n_{l^2})$

$$= \begin{cases} 0 & (n_1, \dots, n_{k^2}) = 0 \\ 1 + \min_{(s_1, \dots, s_{k^2}) \in C} \text{OPT}(n_1 - s_1, \dots, n_{k^2} - s_{k^2}) & (n_1, \dots, n_{k^2}) \geq 0 \\ \infty & \text{otw.} \end{cases}$$

where C is the set of all configurations.

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Can we do better?

Scheduling on identical machines with the goal of minimizing Makespan is a strongly NP-complete problem.

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- Suppose we have an instance with polynomially bounded processing times p_i ≤ q(n)
- ▶ We set $k := \lceil 2nq(n) \rceil \ge 2 \text{ OPT}$
- ▶ Then

$$\mathsf{ALG} \leq \left(1 + \frac{1}{k}\right)\mathsf{OPT} \leq \mathsf{OPT} + \frac{1}{2}$$

- But this means that the algorithm computes the optimal solution as the optimum is integral.
- This means we can solve problem instances if processing times are polynomially bounded
- ▶ Running time is $\mathcal{O}(\text{poly}(n, k)) = \mathcal{O}(\text{poly}(n))$
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More General

Let $\mathrm{OPT}(n_1,\ldots,n_A)$ be the number of machines that are required to schedule input vector (n_1,\ldots,n_A) with Makespan at most T (A: number of different sizes).

If $OPT(n_1, ..., n_A) \le m$ we can schedule the input.

$$\begin{aligned} \text{OPT}(n_1,\ldots,n_A) \\ &= \left\{ \begin{array}{ll} 0 & (n_1,\ldots,n_A) = 0 \\ 1 + \min\limits_{(s_1,\ldots,s_A) \in C} \text{OPT}(n_1-s_1,\ldots,n_A-s_A) & (n_1,\ldots,n_A) \geqslant 0 \\ \infty & \text{otw.} \end{array} \right. \end{aligned}$$

where C is the set of all configurations

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The running time is then $O((B+1)^A n^A)$ because the dynamic programming table has just n^A entries.

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