## 12 Augmenting Path Algorithms

## Greedy-algorithm:

- start with $f(e)=0$ everywhere
- find an $s$ - $t$ path with $f(e)<c(e)$ on every edge
- augment flow along the path
- repeat as long as possible


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## The Residual Graph

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- $G_{f}$ has edge $e_{1}^{\prime}$ with capacity $\max \left\{0, c\left(e_{1}\right)-f\left(e_{1}\right)+f\left(e_{2}\right)\right\}$ and $e_{2}^{\prime}$ with with capacity $\max \left\{0, c\left(e_{2}\right)-f\left(e_{2}\right)+f\left(e_{1}\right)\right\}$.


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\begin{aligned}
& \hline \text { Algorithm } 45 \text { FordFulkerson }(G=(V, E, c)) \\
& \hline \text { 1: Initialize } f(e) \leftarrow 0 \text { for all edges. } \\
& \text { 2: while } \exists \text { augmenting path } p \text { in } G_{f} \text { do } \\
& \text { 3: } \quad \text { augment as much flow along } p \text { as possible. }
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## Proof.

Let $f$ be a flow. The following are equivalent:

1. There exists a cut $A, B$ such that $\operatorname{val}(f)=\operatorname{cap}(A, B)$.

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## Proof.

Let $f$ be a flow. The following are equivalent:

1. There exists a cut $A, B$ such that $\operatorname{val}(f)=\operatorname{cap}(A, B)$.
2. Flow $f$ is a maximum flow.
3. There is no augmenting path w.r.t. $f$.

## Augmenting Path Algorithm

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This we already showed.

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- Let $f$ be a flow with no augmenting paths.
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If there were an augmenting path, we could improve the flow.
Contradiction.
3. $\Rightarrow 1$.

- Let $f$ be a flow with no augmenting paths.
- Let $A$ be the set of vertices reachable from $s$ in the residual graph along non-zero capacity edges.
- Since there is no augmenting path we have $s \in A$ and $t \notin A$.


## Augmenting Path Algorithm

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This finishes the proof.

Here the first equality uses the flow value lemma, and the second exploits the fact that the flow along incoming edges must be 0 as the residual graph does not have edges leaving $A$.

## Analysis

## Assumption:

All capacities are integers between 1 and $C$.

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All capacities are integers between 1 and $C$.
Invariant:
Every flow value $f(e)$ and every residual capacity $c_{f}(e)$ remains integral troughout the algorithm.

## Lemma 53

The algorithm terminates in at most $\operatorname{val}\left(f^{*}\right) \leq n C$ iterations, where $f^{*}$ denotes the maximum flow. Each iteration can be implemented in time $\mathcal{O}(m)$. This gives a total running time of $\mathcal{O}(\mathrm{nmC})$.

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Theorem 54
If all capacities are integers, then there exists a maximum flow for which every flow value $f(e)$ is integral.

## A bad input

Problem: The running time may not be polynomial.


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Question:
Can we tweak the algorithm so that the running time is polynomial in the input length?

## A Pathological Input

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Running time may be infinite!!!

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- Choose path with maximum bottleneck capacity.
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- Choose the shortest augmenting path.
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## Overview: Shortest Augmenting Paths

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## Lemma 55

The length of the shortest augmenting path never decreases.

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## Lemma 56

After at most $\mathcal{O}(m)$ augmentations, the length of the shortest augmenting path strictly increases.

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Proof.

- We can find the shortest augmenting paths in time $\mathcal{O}(m)$ via BFS.
- $\mathcal{O}(m)$ augmentations for paths of exactly $k<n$ edges.


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Note:
There always exists a set of $m$ augmentations that gives a maximum flow.

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However, we can improve the running time to $\mathcal{O}\left(m n^{2}\right)$ by improving the running time for finding an augmenting path (currently we assume $\mathcal{O}(m)$ per augmentation for this).

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With each augmentation some edges are deleted from $E_{L}$.
When $E_{L}$ does not contain an $s$ - $t$ path anymore the distance between $s$ and $t$ strictly increases.

Note that $E_{L}$ is not the set of edges of the level graph but a subset of level-graph edges.

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Either you find $t$ after at most $n$ steps, or you end at a node $v$ that does not have any outgoing edges.

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Either you find $t$ after at most $n$ steps, or you end at a node $v$ that does not have any outgoing edges.

You can delete incoming edges of $v$ from $E_{L}$.

Let a phase of the algorithm be defined by the time between two augmentations during which the distance between $s$ and $t$ strictly increases.

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The total cost for performing an augmentation during a phase is only $\mathcal{O}(n)$. For every edge in the augmenting path one has to update the residual graph $G_{f}$ and has to check whether the edge is still in $E_{L}$ for the next search.

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There are at most $n$ phases. Hence, total cost is $\mathcal{O}\left(m n^{2}\right)$.

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## Capacity Scaling

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## Capacity Scaling

```
Algorithm 46 maxflow \((G, s, t, c\) )
    1: foreach \(e \in E\) do \(f_{e} \leftarrow 0\);
2: \(\Delta \leftarrow 2^{\left\lceil\log _{2} C\right\rceil}\)
    3: while \(\Delta \geq 1\) do
    4: \(\quad G_{f}(\Delta) \leftarrow \Delta\)-residual graph
    5: \(\quad\) while there is augmenting path \(P\) in \(G_{f}(\Delta)\) do
6: \(\quad f \leftarrow \operatorname{augment}(f, c, P)\)
7: \(\quad\) update \(\left(G_{f}(\Delta)\right)\)
8: \(\quad \Delta \leftarrow \Delta / 2\)
9: return \(f\)
```


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Correctness:
The algorithm computes a maxflow:

- because of integrality we have $G_{f}(1)=G_{f}$


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All flows and capacities are/remain integral throughout the algorithm.

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The algorithm computes a maxflow:

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- An $s$ - $t$ cut in $G_{f}(\Delta)$ gives me an upper bound on the amount of flow that my algorithm can still add to $f$.
- The edges that currently have capacity at most $\Delta$ in $G_{f}$ form an $s-t$ cut with capacity at most $2 m \Delta$.


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Theorem 63
We need $\mathcal{O}(m \log C)$ augmentations. The algorithm can be implemented in time $\mathcal{O}\left(m^{2} \log C\right)$.

