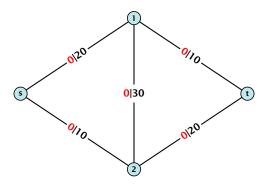
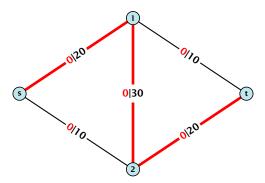
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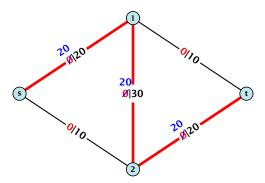


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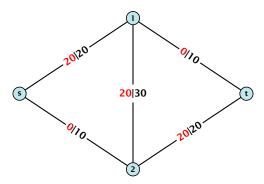


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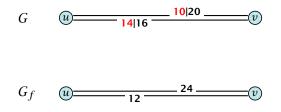


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12.1 Generic Augmenting Path

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Definition 50 An augmenting path with respect to flow f, is a path in the auxiliary graph G_f that contains only edges with non-zero capacity.





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Algorithm 45 FordFulkerson(G = (V, E, c))

- 1: Initialize $f(e) \leftarrow 0$ for all edges.
- 2: while \exists augmenting path p in G_f do
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Theorem 51

A flow f is a maximum flow **iff** there are no augmenting paths.

Theorem 52

The value of a maximum flow is equal to the value of a minimum cut.

Proof.

Let f be a flow. The following are equivalent:

- There exists a cut $A_{i}B$ such that $val(f) = cap(A_{i}B)$.
- 2. Flow f is a maximum flow.
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 $1. \Rightarrow 2.$

This we already showed.

 $2. \Rightarrow 3.$

If there were an augmenting path, we could improve the flow. Contradiction.

- Let f be a flow with no augmenting paths.
- Let A be the set of vertices reachable from 3 in the residual graph along non-zero capacity edges.
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12.1 Generic Augmenting Path

$$\operatorname{val}(f) = \sum_{e \in \operatorname{out}(A)} f(e) - \sum_{e \in \operatorname{into}(A)} f(e)$$



12.1 Generic Augmenting Path

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$$= \operatorname{cap}(A, V \setminus A)$$

This finishes the proof.

Here the first equality uses the flow value lemma, and the second exploits the fact that the flow along incoming edges must be 0 as the residual graph does not have edges leaving A.



Analysis

Assumption: All capacities are integers between 1 and C.

Invariant: Every flow value f(e) and every residual capacity $c_f(e)$ remains integral troughout the algorithm.



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Lemma 53

The algorithm terminates in at most $val(f^*) \le nC$ iterations, where f^* denotes the maximum flow. Each iteration can be implemented in time O(m). This gives a total running time of O(nmC).

Theorem 54

If all capacities are integers, then there exists a maximum flow for which every flow value *f* (e) is integral.



Lemma 53

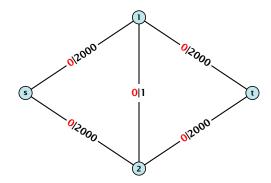
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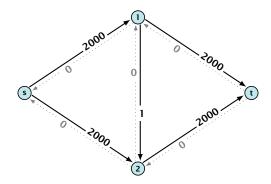
Problem: The running time may not be polynomial.





12.1 Generic Augmenting Path

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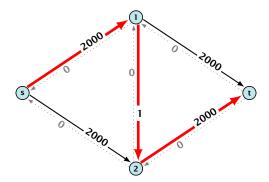
Question:

Can we tweak the algorithm so that the running time is polynomial in the input length?



12.1 Generic Augmenting Path

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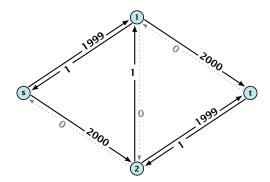
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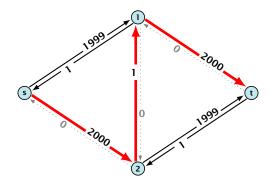
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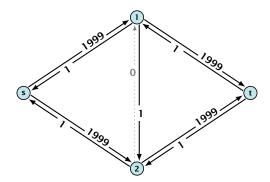
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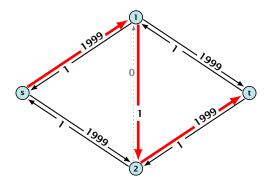
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12.1 Generic Augmenting Path

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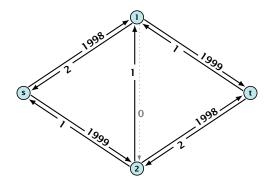
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12.1 Generic Augmenting Path

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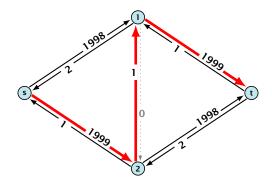
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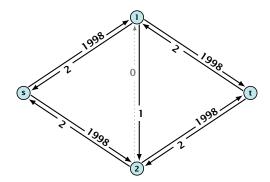
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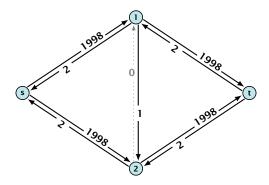
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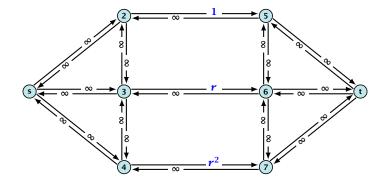
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. Then $r^{n+2} = r^n - r^{n+1}$.

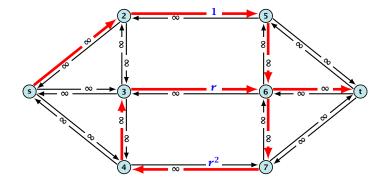




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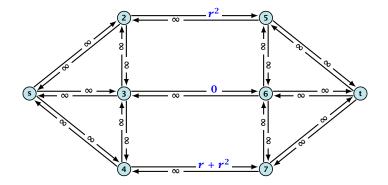




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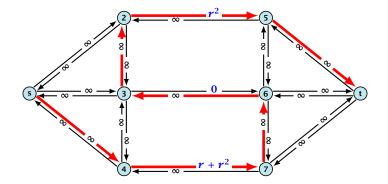




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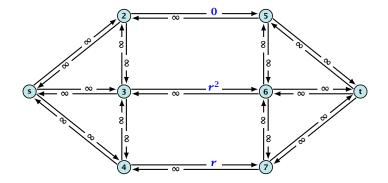




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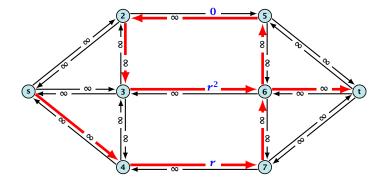




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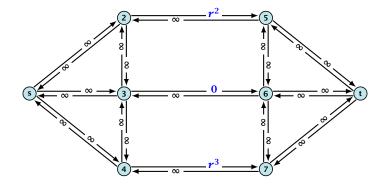




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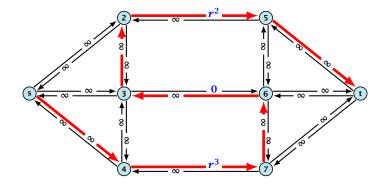




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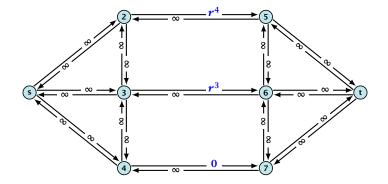




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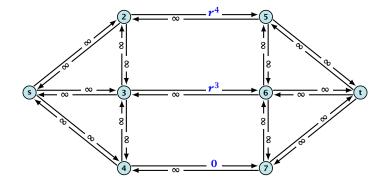




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Running time may be infinite!!!



12.1 Generic Augmenting Path

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12.1 Generic Augmenting Path

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12.1 Generic Augmenting Path

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- Choose the shortest augmenting path.





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Overview: Shortest Augmenting Paths

Lemma 55

The length of the shortest augmenting path never decreases.

Lemma 56

After at most O(m) augmentations, the length of the shortest augmenting path strictly increases.



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These two lemmas give the following theorem:

Theorem 57

The shortest augmenting path algorithm performs at most O(mn) augmentations. This gives a running time of $O(m^2n)$.

Proof.

- We can find the shortest augmenting paths in time $\mathcal{O}(m)$ via BF5.
- $\mathcal{O}(m)$ augmentations for paths of exactly k < n edges.



12.2 Shortest Augmenting Paths

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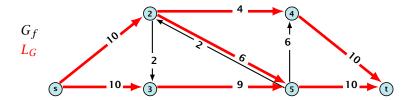
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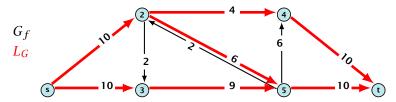
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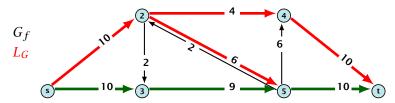
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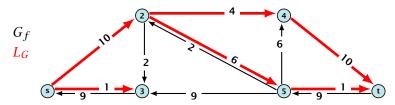
12.2 Shortest Augmenting Paths

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First Lemma: The length of the shortest augmenting path never decreases.

- ► After an augmentation the following changes are done in *G*_{*f*}.
- Some edges of the chosen path may be deleted (bottleneck edges).
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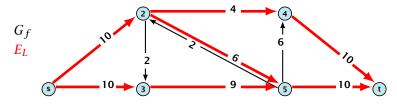


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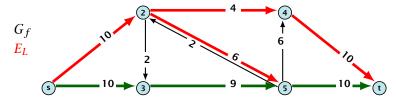
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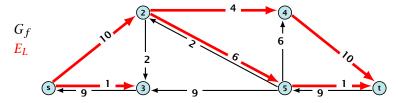
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Theorem 58

The shortest augmenting path algorithm performs at most O(mn) augmentations. Each augmentation can be performed in time O(m).

Theorem 59 (without proof)

There exist networks with $m = \Theta(n^2)$ that require O(mn) augmentations, when we restrict ourselves to only augment along shortest augmenting paths.

Note:

There always exists a set of m augmentations that gives a maximum flow.



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We maintain a subset E_L of the edges of G_f with the guarantee that a shortest *s*-*t* path using only edges from E_L is a shortest augmenting path.

With each augmentation some edges are deleted from E_L .

When E_L does not contain an *s*-*t* path anymore the distance between *s* and *t* strictly increases.

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 E_L is initialized as the level graph L_G .

Perform a DFS search to find a path from s to t using edges from E_L .

Either you find t after at most n steps, or you end at a node v that does not have any outgoing edges.

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Initializing E_L for the phase takes time O(m).

The total cost for searching for augmenting paths during a phase is at most O(mn), since every search (successful (i.e., reaching t) or unsuccessful) decreases the number of edges in E_L and takes time O(n).

The total cost for performing an augmentation during a phase is only $\mathcal{O}(n)$. For every edge in the augmenting path one has to update the residual graph G_f and has to check whether the edge is still in E_L for the next search.

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We need to find paths efficiently.

Several possibilities:



12.3 Capacity Scaling

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- Choose path with maximum bottleneck capacity.
- Choose path with sufficiently large bottleneck capacity.
- Choose the shortest augmenting path.



12.3 Capacity Scaling

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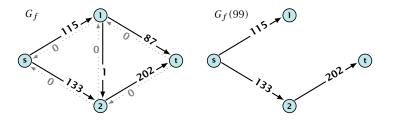


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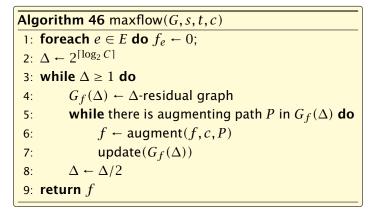
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- this means we have a maximum flow.





12.3 Capacity Scaling

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12.3 Capacity Scaling

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Theorem 63 We need $O(m \log C)$ augmentations. The algorithm can be implemented in time $O(m^2 \log C)$.

