Algorithm 50 highest-label (G, s, t)

- 1: initialize preflow
- 2: **foreach** $u \in V \setminus \{s, t\}$ **do**
- 3: $u.current-neighbour \leftarrow u.neighbour-list-head$
- 4: **while** \exists active node u **do**
- select active node u with highest label
- 6: $\operatorname{discharge}(u)$

Lemma 80

When using highest label the number of non-saturating pushes is only $\mathcal{O}(n^3)$.

After a non-saturating push from u a relabel is required to make a currently non-active node x, with $\ell(x) \ge \ell(u)$ active again (note that this includes u).

Hence, after n non-saturating pushes without an intermediate relabel there are no active nodes left.

Therefore, the number of non-saturating pushes is at most $n(\#relabels + 1) = O(n^3)$.

Since a discharge-operation is terminated by a non-saturating push this gives an upper bound of $\mathcal{O}(n^3)$ on the number of discharge-operations.

The cost for relabels and saturating pushes can be estimated in exactly the same way as in the case of relabel-to-front.

Question:

How do we find the next node for a discharge operation?

Maintain lists L_i , $i \in \{0, ..., 2n\}$, where list L_i contains active nodes with label i (maintaining these lists induces only constant additional cost for every push-operation and for every relabel-operation).

After a discharge operation terminated for a node u with label k, traverse the lists $k-1,\ldots,0$, (in that order) until you find a non-empty list.

Unless the last (non-saturating) push was to s or t the list k-1 must be non-empty (i.e., the search takes constant time).

Hence, the total time required for searching for active nodes is at most

$$\mathcal{O}(n^3) + n(\#non\text{-}saturating\text{-}pushes\text{-}to\text{-}s\text{-}or\text{-}t)$$

Lemma 81

The number of non-saturating pushes to s or t is at most $\mathcal{O}(n^2)$.

With this lemma we get

Theorem 82

The push-relabel algorithm with the rule highest-label takes time $\mathcal{O}(n^3)$.

Proof of the Lemma.

- We only show that the number of pushes to the source is at most $\mathcal{O}(n^2)$. A similar argument holds for the target.
- After a node v (which must have $\ell(v) = n+1$) made a non-saturating push to the source there needs to be another node whose label is increased from $\leq n+1$ to n+2 before v can become active again.
- This happens for every push that v makes to the source. Since, every node can pass the threshold n + 2 at most once, v can make at most n pushes to the source.
- As this holds for every node the total number of pushes to the source is at most $\mathcal{O}(n^2)$.