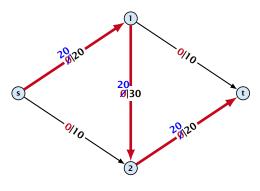
## 12

## Greedy-algorithm:

- ightharpoonup start with f(e) = 0 everywhere
- find an s-t path with f(e) < c(e) on every edge
- augment flow along the path
- repeat as long as possible



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## The Residual Graph

From the graph G = (V, E, c) and the current flow f we construct an auxiliary graph  $G_f = (V, E_f, c_f)$  (the residual graph):

- Suppose the original graph has edges  $e_1 = (u, v)$ , and  $e_2 = (v, u)$  between u and v.
- ▶  $G_f$  has edge  $e_1'$  with capacity  $\max\{0, c(e_1) f(e_1) + f(e_2)\}$  and  $e_2'$  with with capacity  $\max\{0, c(e_2) f(e_2) + f(e_1)\}$ .

G  $u \longrightarrow v$ 

 $G_f$   $u \longrightarrow v$ 

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12.1 The Generic Augmenting Path Algorithm

. . . .

# **Augmenting Path Algorithm**

## **Definition 1**

An augmenting path with respect to flow f, is a path from s to t in the auxiliary graph  $G_f$  that contains only edges with non-zero capacity.

**Algorithm 46** FordFulkerson(G = (V, E, c))

- 1: Initialize  $f(e) \leftarrow 0$  for all edges.
- 2: while  $\exists$  augmenting path p in  $G_f$  do
- 3: augment as much flow along p as possible.

# **Augmenting Path Algorithm**

Animation for augmenting path algorithms is only available in the lecture version of the slides.

# **Augmenting Path Algorithm**

## **Theorem 2**

A flow f is a maximum flow **iff** there are no augmenting paths.

### Theorem 3

The value of a maximum flow is equal to the value of a minimum cut.

## Proof.

Let f be a flow. The following are equivalent:

- 1. There exists a cut A, B such that val(f) = cap(A, B).
- **2.** Flow f is a maximum flow.
- **3.** There is no augmenting path w.r.t. f.

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12.1 The Generic Augmenting Path Algorithm

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# **Augmenting Path Algorithm**

$$val(f) = \sum_{e \in out(A)} f(e) - \sum_{e \in into(A)} f(e)$$
$$= \sum_{e \in out(A)} c(e)$$
$$= cap(A, V \setminus A)$$

This finishes the proof.

Here the first equality uses the flow value lemma, and the second exploits the fact that the flow along incoming edges must be 0 as the residual graph does not have edges leaving A.

## **Augmenting Path Algorithm**

 $1. \Rightarrow 2.$ 

This we already showed.

 $2. \Rightarrow 3.$ 

If there were an augmenting path, we could improve the flow. Contradiction.

- $3. \Rightarrow 1.$ 
  - Let *f* be a flow with no augmenting paths.
  - Let *A* be the set of vertices reachable from *s* in the residual graph along non-zero capacity edges.
  - ▶ Since there is no augmenting path we have  $s \in A$  and  $t \notin A$ .

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# **Analysis**

## Assumption:

All capacities are integers between 1 and  $\mathcal{C}$ .

## Invariant:

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Every flow value f(e) and every residual capacity  $c_f(e)$  remains integral troughout the algorithm.

### Lemma 4

The algorithm terminates in at most  $val(f^*) \leq nC$  iterations, where  $f^*$  denotes the maximum flow. Each iteration can be implemented in time O(m). This gives a total running time of  $\mathcal{O}(nmC)$ .

#### Theorem 5

If all capacities are integers, then there exists a maximum flow for which every flow value f(e) is integral.

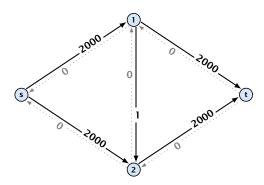
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# **A Bad Input**

Problem: The running time may not be polynomial.



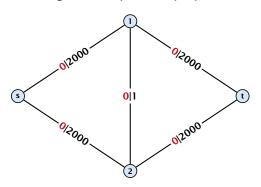
Question:

Can we tweak the algorithm so that the running time is polynomial in the input length?

See the lecture-version of the slides for the animation.

# **A Bad Input**

Problem: The running time may not be polynomial.



Ouestion:

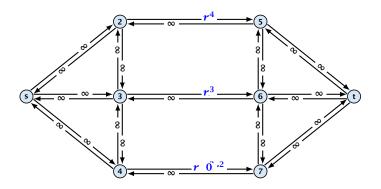
Can we tweak the algorithm so that the running time is polynomial in the input length?

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12.1 The Generic Augmenting Path Algorithm

# **A Pathological Input**

Let  $r = \frac{1}{2}(\sqrt{5} - 1)$ . Then  $r^{n+2} = r^n - r^{n+1}$ .



Running time may be infinite!!!

See the lecture-version of the slides for the animation.

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# How to choose augmenting paths? ► We need to find paths efficiently. ▶ We want to guarantee a small number of iterations. Several possibilities: ► Choose path with maximum bottleneck capacity. ▶ Choose path with sufficiently large bottleneck capacity. ► Choose the shortest augmenting path. EADS © Ernst Mayr, Harald Räcke 12.1 The Generic Augmenting Path Algorithm 452